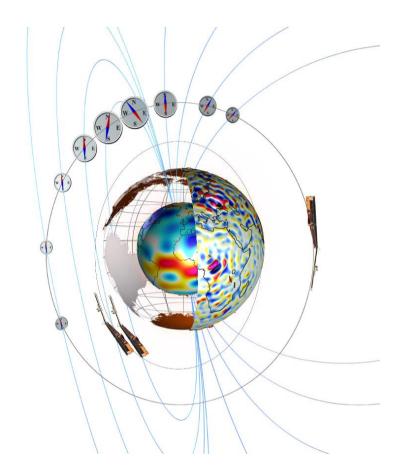






# Swarm DISC Weekly Report 2019/48: 2019/11/25 - 2019/12/01



**Abstract**: This is the **Swarm Data Innovation and Science Cluster** (Swarm DISC) Weekly report on Swarm products quality, covering the period from 25 November to 01 December 2019.

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# **AMENDMENT POLICY**

This document shall be amended by releasing a new edition of the document in its entirety. The Amendment Record Sheet below records the history and issue status of this document.

#### **AMENDMENT RECORD SHEET**

ISSUE	DATE	REASON
1.0	13 Dec 2019	First issue







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#### 1. Introduction

This document refers to the activities carried out in the framework of the ESA Sensor Performance, Products and Algorithms (SPPA) Office [RD.1].

Chapter 1 gives an overview on the outcomes from the annual Swarm Data Quality Workshop and reports the information on the current operational configuration and its future improvements. It also contains the list of used reference documents.

In Chapter 2, the Section 2.1 gives an overview of the general quality status of the Swarm mission instruments and products, while the main observations of the week are summarized in the Section 2.2.

The document also includes information on data quality for the three Swarm spacecraft, inferred from automated HTML quality reports, which are produced on daily basis for each product. If interested in accessing the reports via web or FTP, please contact the Swarm DISC team at the following email address: <swarm@eo-sppa.org>. Such data quality reports represent the main component of the Routine Quality Control performed by ESA SPPA (Chapter 3). A description of the implemented quality checks is given in [RD.2], and references therein.

Based on specific findings of the routine quality control, or requests from other entities (i.e. Swarm Payload Data Ground Segment (PDGS), Flight Operation Segment (FOS), Mission Management, Post-Launch Support Office (PLSO), Expert Support Laboratories (ESL), Quality Working Groups (QWG), and user community), investigations on anomalies can be triggered. Preliminary characterisations on such anomalies are given in Chapter 4.

Information on Swarm Level 1B products can be found in [RD.3].

This weekly report is based on QC methods and diagnostics that tend to be continuously evolved and improved throughout the mission lifetime, reporting on the data quality, product evolutions, and status of the instruments on weekly basis.

#### 1.1 Annual Swarm Data Quality Workshop

The 9th Swarm Data Quality Workshop (DQW#9) was held in Prague (Czech Republic) from 16 to 20 September 2019.

This workshop was focussed on Swarm payload performance, their product status and on the use of Swarm data to define a road map for identifying and selecting new Swarm data products and services, prioritizing future Swarm-related research activities, and for collecting inputs for the optimization of the orbital constellation in view of addressing a wide spectrum of applications.

The DQW#9 had eleven thematic sessions mainly related to:

- Swarm L1B data products and cal/val activities
- Internal/external field variations
- Swarm-based Multi-mission synergies
- Space Sciences/Weather perspectives and future challenges
- Time series analysis tools used in Swarm data processing

A complete summary of the recommendations based on the contributions from Swarm DQW#9 sessions will be published soon. More info on the Agenda and presentations are available at [RD.6].







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# 1.2 Current Operational configuration of monitored data:

Processor			
Name	Version		
L1BOP	v3.20p1		
L2-Cat2	v01.18p2		
Products			
Name	Baseline		
L0 inputs	02		
L1B MAGNET and PLASMA	05		
L1B ORBATT and ACCELE	04		
L2-Cat2 EEF*	01		
L2-Cat2 IBI, FAC and TEC	03		
Others			
Input auxiliary files	S/C A, CCDB 0022 (06/03/2019)		
	S/C B, CCDB 0022 (02/01/2019)		
	S/C C, CCDB 0023 (06/03/2019)		
	ADF 0101		
MPPF-CVQ	v03.07 (27/12/2018)		

#### 1.3 **Recent evolutions:**

The L1BOP v03.21 (delivered on 11/03/2019) and L2 Cat-2 OP v01.19 (delivered on 13/03/2019) contain only the porting to a newer operational system, Red Hat Enterprise Linux 7.5. No evolutions of the processor algorithms are included in these deliveries. The verification processor was concluded by both the Swarm PDGS team and Swarm Data quality team. During such verification process, the Swarm Data Quality Team detected few very small discrepancies while analysing the following products: STRxATT\_1B (delta\_q ~ 10^-9), ASMx\_AUX\_1B, MAGx\_CA\_1B, MAGx\_HR\_1B, MAGx\_LR\_1B (differences in the position within 1 cm and in the magnetic field components within 0.5 pT). In conclusion, all the discrepancies found are considered fully negligible (conclusion reached together with the PP providers). No issue is considered critical or blocking for the deployment in operations of these processors.

In the meantime, an improved version of the L1BOP (v03.22) has been delivered on 22/08/2019. The main evolutions of this operational processor consist in:

- MAGNET: Reading of ASMxBUR\_0\_ files to generate ASM 1Hz data during ASM burst mode sessions.
- ORBATT: Improving the combination of the three STR attitude quaternions into the combined attitude solution.
- PLASMA: Retrieving the information on the S/C position from MODx\_SC\_1B data product, instead of from MAGx\_LR\_1B and MAG\_HR\_1B data products.

The PDGS Team will generate the test scenarios in order to compare their outputs with the ones from GMV. Then, the Data Quality Team will finalize the cross-verification of the processor.

<sup>\*</sup> The production of the EEF product is temporarily suspended.







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#### 1.4 Reference documents

The following is a list of documents with a direct bearing on the content of this report. Where referenced in the text, these are identified as RD.n, where 'n' is the number in the list below:

- [RD.1] Sensor Performance, Products and Algorithms (SPPA), PGSI-GSOP-EOPG-TN-05-0025. Version 2.3.
- [RD.2] Swarm MPPF-CVQ Monitoring Baseline Document, ST-ESA-SWARM-MBD-0001, Issue 1.7.
- [RD.3] Swarm Level 1B Product Definition, SW-RS-DSC-SY-0007, Issue 5.13.
- [RD.4] Olsen, N., H. Luhr, C.C. Finlay, T.J. Sabaka, I. Michaelis, J. Rauberg and L. Tøffner-Clausen, The CHAOS-4 geomagnetic field model, Geophys. J. Int. 197, 815–827, 2014
- [RD.5] SW-RP-SER-GS-010\_SPPA\_SwarmWeeklyReport\_201641\_20161010\_20161016.pdf
- [RD.6] <a href="https://earth.esa.int/web/guest/missions/esa-eo-missions/swarm/activities/conferences/9th-data-quality-workshop">https://earth.esa.int/web/guest/missions/esa-eo-missions/swarm/activities/conferences/9th-data-quality-workshop</a>
- [RD.7] SW-RP-SER-GS-010\_SPPA\_SwarmWeeklyReport\_201940\_20190930\_20191006.pdf







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# 2. Summary of the observations

# 2.1 Changes in the general status of Swarm instruments and Level 1B products quality

The ASM (Absolute Scalar Magnetometer) on board Swarm Bravo was commanded in burst mode from 24/11/2019 at 23:50 UTC to 02/12/2019 at 00:10 UTC.

A series of Yaw and Pitch manoeuvres with Swarm-B was successfully executed on 27/11/2019 in order to calibrate the EFI TII instrument, as performed in 2014 during the commissioning phase (and in Swarm-A on 30/09/2019, see [RD.7]). The execution took place in two different orbits between 01:30 UTC and 06:30 UTC.

A series of Yaw and Pitch manoeuvres with Swarm-C was successfully executed on 26/11/2019 in order to calibrate the EFI TII instrument, as performed in 2014 during the commissioning phase(and in Swarm-A on 30/09/2019, see [RD.7]). The execution took place in two different orbits between 04:47 UTC and 06:58 UTC.

# 2.2 Relevant observations of the week 48 (25/11 - 01/12)

During the monitored week the following events have been found:

- Data gap was detected in the VC4 dump on 29/11/2019 for Swarm Bravo. The affected data generation time is between 05:11:49 and 05:11:51 UTC. Time gaps found in HK\_BNOM\_0\_, VFMBNOM\_0\_, GPSBOBS\_0\_, GPSBNAV\_0\_, EFIBNOM\_0\_, ASMBBUR\_0\_ products, affecting GPS 1B, magnet L1A and L1B data products.
- On SC A on days 25/12-01/12/2019, mean and VFM-ASM residuals values are out of thresholds, due to discrepancies between ASM and VFM.







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# 3. Routine Quality control

## 3.1 Gaps analysis

- Time gaps found in STRBNOM\_0\_, HK\_BNOM\_0\_, ASMBBUR\_0\_ products on day 26/11/2019 for Swarm Bravo between 19:40:19-19:40:29 UTC. It affects MAGB CA 1B, EFIB LP 1A.
- Data gap was detected in the VC4 dump on 29/11/2019 for Swarm Bravo. The affected data generation time is between 05:11:49 and 05:11:51 UTC. Time gaps found in HK\_BNOM\_0\_, VFMBNOM\_0\_, GPSBOBS\_0\_, GPSBNAV\_0\_, EFIBNOM\_0\_, ASMBBUR\_0\_ products, affecting GPS 1B, magnet L1A and L1B data products.

#### 3.2 **Orbit and Attitude Products**

The relevant parameters that have been monitored are:

- Position difference between calculated Medium Accuracy orbits (MODx\_SC\_1B) and on-board solution (GPSxNAV\_0). Threshold values for such differences have not been assessed yet: we have just monitored the average values and maximum variations within the week. They are reported in tables in the sections below. In addition, some example plots are given from the HTML daily reports. For the time being we evaluated an anomaly should be raised if one (or more) of the following conditions occurs:
  - The average difference on a given day exceeds the position accuracy requirement for the mission (1.5 m),
  - The variability around the average is quite high: standard deviation threshold has been arbitrarily chosen to be twice the position accuracy requirement for the mission (2-sigma = 3 m).
  - o At least 4-5 spikes are observed on a given day, exceeding +/- 50 m.
- Visual inspection of Star Tracker characterisation flags (STRxATT\_1B)
- Deviation of the quaternion norm from unity (deviation threshold =  $\pm$ /- 10<sup>-9</sup>)
- Visual inspection of Euler Angles derived from quaternions.

#### 3.2.1 **Position Statistics**

In Figure 3-1 one can see the statistics of the differences between MOD and on-board solution positions for S/C A, B and C respectively. In the third column the maximum differences (maximum negative and maximum positive) are reported. The standard deviation is in the fourth column. Maxima, minima and standard deviations usually refer to the Z component that is often the most disturbed; in case another component is most affected, it will be specified in parentheses. Figure 3-1 shows a cumulative trend of the maximum daily standard deviation for the past 30 days of operations of the MOD-NAV difference, while Figure 3-2 shows the daily maximum difference, in absolute value, of the MOD-NAV difference, always for the past 30 days of operations.

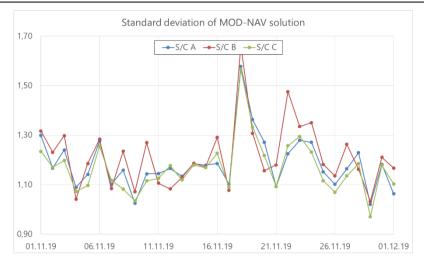




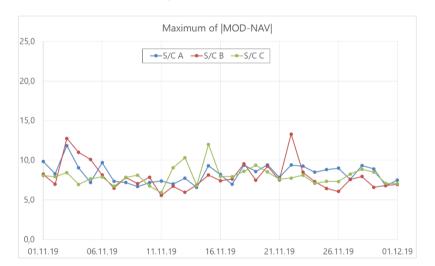


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**Figure 3-1:** Plot of the standard deviation of the difference between MOD and NAV solutions for all satellites. Plot covers last month of operation.



**Figure 3-2:** Plot of the maximum difference of the absolute value of the difference between MOD and NAV solutions for all satellites. Plot covers last month of operation.

#### 3.2.2 **Attitude observations**

#### 3.2.2.1 **Swarm A**

Nominal. Nothing to report.

#### 3.2.2.2 **Swarm B**

Flags\_q set to 255 from 08:04:05-08:04:16 on day 29/11/2019.

#### 3.2.2.3 **Swarm C**

Nominal. Nothing to report.







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## 3.3 Magnetic Products

For the magnetic products, the weekly monitoring consists of:

- ASM instrument monitoring: quartz frequency (nominal range: [2.949E7 2.950E7] Hz) and ASM temperature (temperature range shall be: [-30;+50] °C, Rel. Variation shall not exceed: 0.1 °C/sec).
- VFM instrument monitoring: temperatures (Rel. Variation shall not exceed: 0.1 °C/sec).
- Visual inspection of daily time series of magnetic field intensity F, B<sub>NEC</sub> and B<sub>VFM</sub>. Looking for gaps (or zero values in case of MAGx\_LR\_1B products), out-of-threshold values (i.e. exceeding +/- 60000 nT), and other strange features. Map plots of F and B<sub>NEC</sub> for the whole week are then displayed.
- Monitoring of the ASM-VFM known anomaly: visual inspection of |B<sub>VFM</sub>| F taken from MAGx\_CA\_1B products and recording of daily maximum variations and standard deviations. If +/- 1 nT are exceed on a given day, an alert is raised. Map plots of the residuals are shown along with weekly time series of the residuals with and without the "dB\_Sun" correction: in fact, at least a part of the discrepancies found in the measurements between ASM and VFM are modelled through a stray field (dB\_Sun) that is a function of the orientation of the VFM wrt Sun.
- Comparison of magnetic data (B<sub>NEC</sub>) with a model (Chaos6).

#### 3.3.1 **VFM-ASM anomaly**

- S/C A violation of:
  - VFM-ASM residuals threshold on 25/11, 26/11, 27/11, 28/11, 29/11, 30/11, 01/12;
  - o mean value of residuals threshold on 25/11, 26/11, 27/11, 28/11, 29/11, 30/11, 01/12;
- S/C B violation of:
  - VFM-ASM residuals threshold on 25/11, 26/11, 27/11, 28/11, 29/11, 30/11, 01/12;
  - mean value of residuals threshold on 25/11, 26/11, 27/11, 28/11, 29/11, 30/11, 01/12;
  - standard deviation of residuals threshold on 25/11, 26/11, 27/11, 28/11, 29/11, 30/11, 01/12.

#### 3.3.1.1 **ASM-VFM difference statistics**

The ASM-VFM difference is defined as follow:

 $dF = |B_{VFM}| - F_{ASM}$ 

Figure 3-3 and Figure 3-4 show the daily mean (circles) and standard deviation (crosses) of dF of the last month for Swarm A and Swarm B respectively.

Data gaps in Figure 3-4 are due to the ASM (Absolute Scalar Magnetometer) on board Swarm Bravo commanded in burst mode from 24/11/2019 at 23:50 UTC to 02/12/2019 at 00:10 UTC (see Section 2).

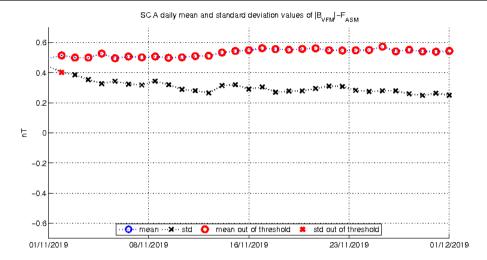




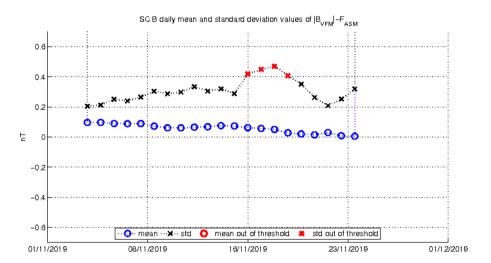


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**Figure 3-3:** Daily mean and standard deviation values of ASM-VFM residuals (defined as  $dF = |B_{VFM}| - F_{ASM}$ ) for S/C A.



**Figure 3-4:** Daily mean and standard deviation values of ASM-VFM residuals (defined as  $dF = |B_{VFM}| - F_{ASM}$ ) for S/C B.



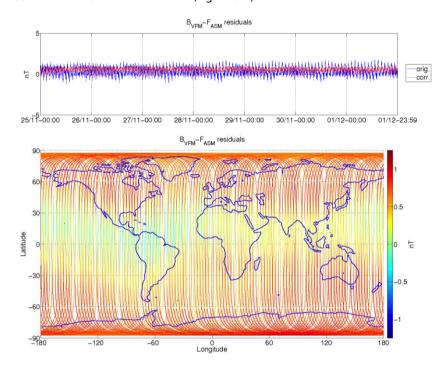




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#### 3.3.1.2 **Swarm A**

The daily peak-to-peak difference around the week stays within [-0,44 - 1,15] nT. Below follow two plots of such differences for current week (Figure 3-5).



**Figure 3-5:** ASM-VFM residuals for S/C A, during monitoring period 25/11-01/12. In top figure are plotted: difference between |B\_VFM| and F\_ASM (without dB\_Sun correction) (blue colour), and the residuals with dB\_Sun corrections (red colour). In bottom figure residuals are presented on the world map.

#### 3.3.1.3 **Swarm B**

No data due to the ASM (Absolute Scalar Magnetometer) on board Swarm Bravo commanded in burst mode from 24/11/2019 at 23:50 UTC to 02/12/2019 at 00:10 UTC (see Section 2).

#### 3.3.1.4 **Swarm C**

No data because ASM is switched off.

# 3.3.2 **ASM Instrument parameters: quartz frequency and ASM temperature** (ASMAVEC\_0)

For S/C A and B, the temperature and quartz frequency behaved as expected.







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# 3.3.3 VFM Instrument parameters: VFM temperatures (MAG\_CA)

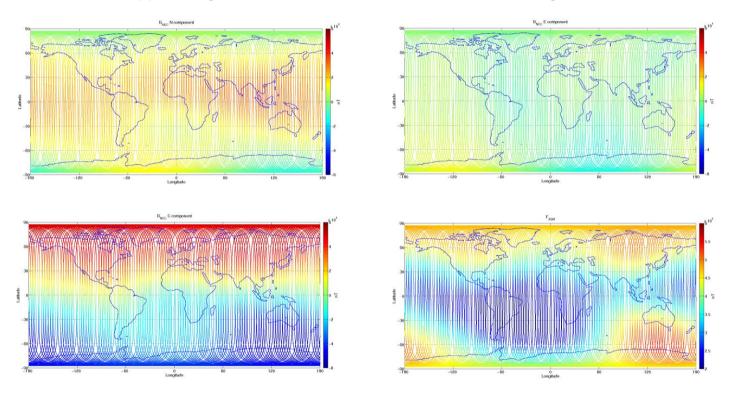
The VFM instrument parameters important for monitoring the instrument health are the VFM sensor temperatures: T\_CDC, T\_CSC and T\_EU.

For S/C A, B and C, for reported period, the temperatures behaved as expected.

# 3.3.4 Magnetic time series visual inspection

#### 3.3.4.1 **Swarm A**

Map plots of magnetic field measurement for week 48 for S/C A can be seen in Figure 3-6 below.



**Figure 3-6:** S/C A, world map plots of the geomagnetic field and components measured during monitoring period 25/11-01/12. From top to bottom: B<sub>NEC</sub> components (North, East, and Centre) of magnetic field from VFM measurement, F-magnetic field from ASM measurement.



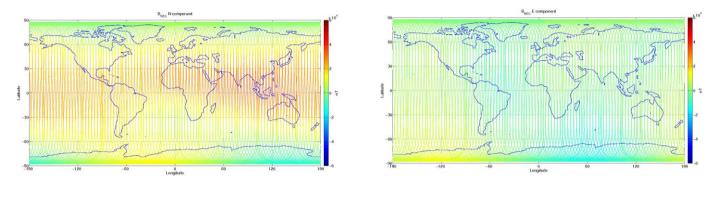


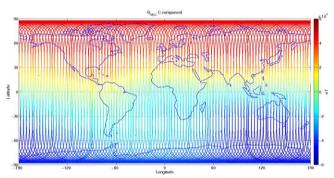


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#### 3.3.4.2 **Swarm B**

Map plots of magnetic field measurement for week 48 for S/C B can be seen in Figure 3-7.





**Figure 3-7:** S/C B, world map plots of the geomagnetic field and components measured during monitoring period 25/11-01/12. From top to bottom:  $B_{NEC}$  components (North, East, and Centre) of magnetic field from VFM measurement



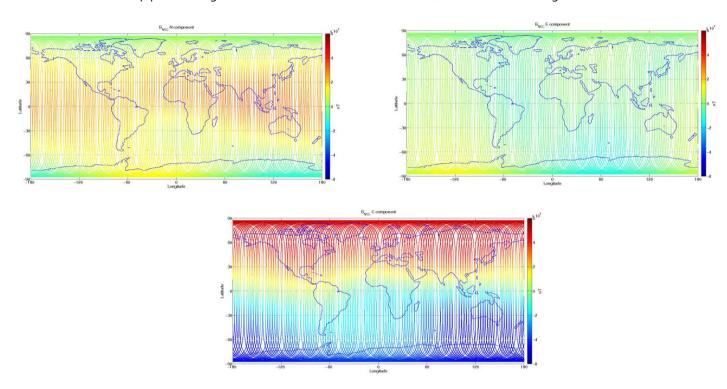




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#### 3.3.4.3 **Swarm C**

Map plots of magnetic field measurement for week 48 for S/C C can be seen in Figure 3-8.



**Figure 3-8:** S/C C, world map plots of the geomagnetic field and components measured during monitoring period 25/11-01/12. From top to bottom: B<sub>NEC</sub> components (North, East, and Centre) of magnetic field from VFM measurement

#### 3.3.5 **B**<sub>NEC</sub> vs Chaos6 model residuals

The magnetic field measurement is compared to magnetic field estimated from the Chaos6 global geomagnetic field model (only Core and Crustal contributions). Currently in the monitoring routines the external contribution based on Dst index is not taken into account.

Left side of Figure 3-9, Figure 3-10 and Figure 3-11 show field residuals  $dB=B_{NEC}$  -  $B_{Chaos}$  (all versus co-latitude in degrees), from top to bottom: 1) Br, 2)  $B\theta$  and 3)  $B\phi$ .

As a general feature one can see the field residuals to be steady and usually below 50 nT at low and middle latitudes, up to |55| - |60| degrees; then the residual increases at high latitudes because the Chaos model does not take into account the contribution from the external field ([RD.4]).

Right side of Figure 3-9, Figure 3-10 and Figure 3-11 show, from top to bottom, the time series on first day of the week of: (1-2-3) residuals of  $B_{NEC}$ - $B_{Chaos}$  by components, related to S/C A, B and C respectively.

The component most affected by residual spikes and variations is  $B\theta_{NEC}$ , i.e. the component that shows the variations of the field wrt to co-latitude. At high latitudes, the order of magnitude of the variability is about +/- 200 nT.







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#### 3.3.5.1 **Swarm A**

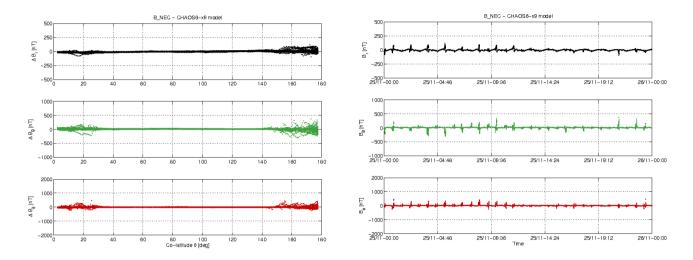


Figure 3-9: S/C A day 25.11: time series of B<sub>NEC</sub> – B<sub>Chaos</sub> residuals (right) and B<sub>NEC</sub> - B<sub>Chaos</sub> vs colatitude (left).

#### 3.3.5.2 **Swarm B**

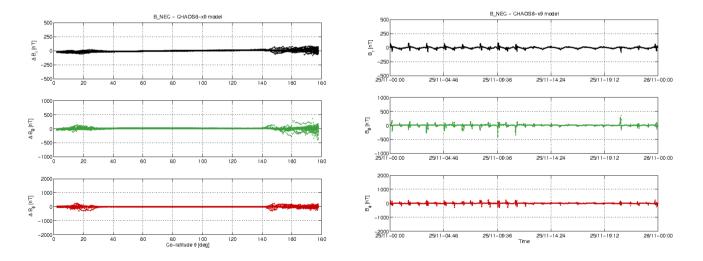


Figure 3-10: S/C B day 25.11: time series of B<sub>NEC</sub> – B<sub>Chaos</sub> residuals (right) and B<sub>NEC</sub> - B<sub>Chaos</sub> vs colatitude (left).







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#### 3.3.5.3 **Swarm C**

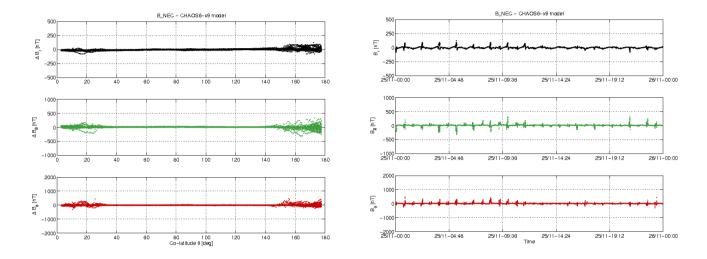


Figure 3-11: S/C C day 25.11: time series of B<sub>NEC</sub> – B<sub>Chaos</sub> residuals (right) and B<sub>NEC</sub> - B<sub>Chaos</sub> vs colatitude (left)

#### 3.4 Plasma Products

The monitored plasma products are the electron density (Ne) and electron temperature (Te) measured by the EFI-LP instruments. The monitoring of the data is done on different temporal basis (daily, weekly, monthly, yearly) in order to have a comprehensive view on the data quality. Here we report only two examples of the performed data monitoring, which are the most representative of the data quality.

Figures from Figure 3-12 to Figure 3-14 show the weekly profiles of the electron density and temperature as a function of time for the last week of operations. Data have been down sampled from 0.5s to 2min in order to have a clearer representation (grey lines). Also, the 20 minutes moving window average is shown in the figures (black points). From these figures, it is possible to see if there are measurements with large discrepancies from the average behaviour, and their time location. Information on the local magnetic time is reported in the captions.

Figures from Figure 3-15 to Figure 3-17 show the variations of the electron density and temperature as a function of the latitudes in quasi-dipole (QD) coordinate system, during the last week of operation. These analyses are useful to study the dependence of the variables on the QD magnetic coordinate system.

These analyses are shown for the ascending (upper panels) and descending (bottom panels) phase orbits, separately.

It is visible that sometimes the electron temperature reaches very high values, exceeding ten thousands Kelvin, particularly at high latitudes. The nature of this feature is currently under investigation.



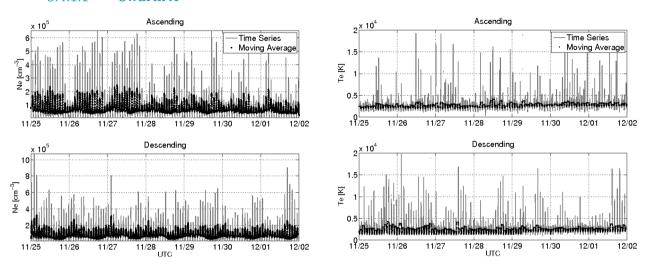




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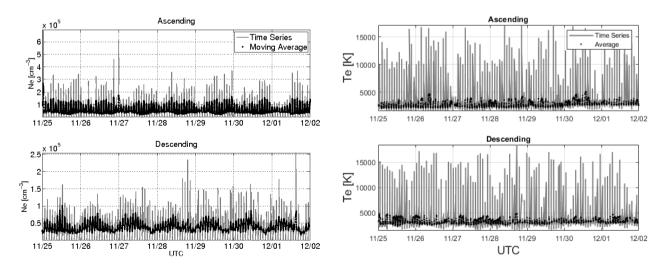
### 3.4.1 Plasma time series visual inspection

#### 3.4.1.1 **Swarm A**



**Figure 3-12:** The panels show the electron density (left) and temperature (right) weekly time series (grey lines) together with the 20 min moving windows average (black lines). The analysis is made separately for ascending (upper panels) and descending (bottom panels) orbits. The average magnetic local time during the week is 9 a.m. for ascending phase and 9 p.m. for descending phase.

#### 3.4.1.2 **Swarm B**



**Figure 3-13:** The panels show the electron density (left) and temperature (right) weekly time series (grey lines) together with the 20 min moving windows average (black lines). The analysis is made separately for ascending (upper panels) and descending (bottom panels) orbits. The average magnetic local time during the week is 6 a.m. for descending phase and 6 p.m. for ascending phase.

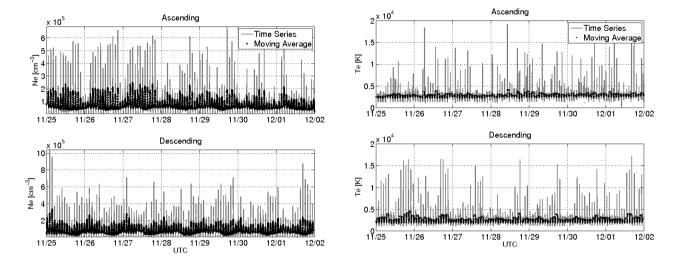






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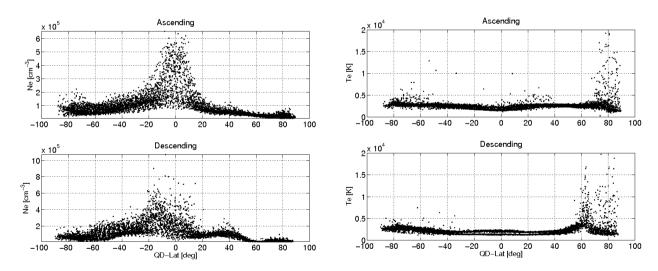
#### 3.4.1.3 **Swarm C**



**Figure 3-14:** The panels show the electron density (left) and temperature (right) weekly time series (grey lines) together with the 20 min moving windows average (black lines). The analysis is made separately for ascending (upper panels) and descending (bottom panels) orbits. The average magnetic local time during the week is 9 a.m. for ascending phase and 9 p.m. for descending phase.

# 3.4.2 Plasma products latitudinal variations

#### 3.4.2.1 **Swarm A**



**Figure 3-15:** The panels shown the electron density (left) and temperature (right) profile as a function of QD Latitudes for the last week of operation. The analysis is made separately for ascending (upper panels) and descending (bottom panels) orbits.

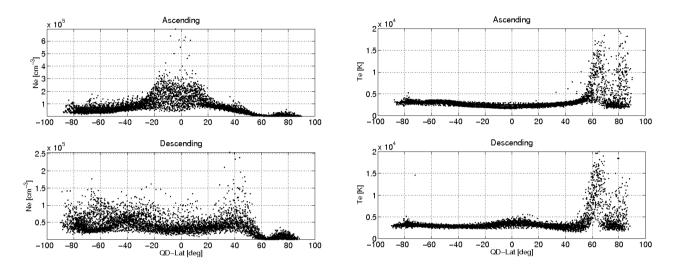






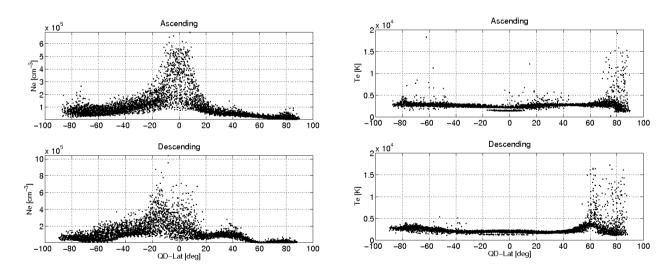
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#### 3.4.2.2 **Swarm B**



**Figure 3-16:** The panels shown the electron density (left) and temperature (right) profile as a function of QD Latitudes for the last week of operation. The analysis is made separately for ascending (upper panels) and descending (bottom panels) orbits.

#### 3.4.2.3 **Swarm C**



**Figure 3-17:** The panels shown the electron density (left) and temperature (right) profile as a function of QD Latitudes for the last week of operation. The analysis is made separately for ascending (upper panels) and descending (bottom panels) orbits.







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# 4. Special Investigations

Nothing to report.







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