



Customer	: ESRIN	Document Ref	: IDEAS+-SER-OQC-REP-2071
Contract No	: 4000111304/14/I-AM	Issue Date	: 12 February 2015
WP No	: 6110	Issue	: 1.0



IDEAS+ Swarm Weekly Report 2015/06 : 02/02/2015 – 08/02/2015

Abstract : This is the **Instrument Data quality Evaluation and Analysis Service Plus** (IDEAS+) Swarm Weekly report on Swarm products quality, covering the period from 2 to 8 February 2015.

Author : _____ **Approval** : _____
Igino Coco, on behalf of Swarm IDEAS+ Team Lidia Saavedra de Miguel
IDEAS+ Science and Ops.
Coordinator

Distribution : ESA/ESRIN EOP-GMQ
ESA/ESRIN EOP-GM Swarm MM
IDEAS+ Leadership Team
IDEAS+ subcontractors
ESA/ESTEC Swarm PLSO
ESA/ESOC Swarm FOS

Copyright © 2015 Serco Italia Spa

All rights reserved.

No part of this work may be disclosed to any third party translated reproduced copied or disseminated in any form or by any means except as defined in the contract or with the written permission of Serco Italia Spa.

Serco Italia Spa
Via Sciadonna 24/26, 00040, Frascati, Italy
Tel: +39 06 98354400 Fax: +39 06 9419426
www.serco.com



TABLE OF CONTENTS

Contents

TABLE OF CONTENTS	2
1. INTRODUCTION.....	5
1.1 Current Operational configuration of monitored data:	6
1.2 Reference documents	6
2. SUMMARY OF THE OBSERVATIONS	8
2.1 General status of Swarm instruments and Level 1B products quality	8
2.2 Plan for operational processor updates	8
2.3 Quality Working Group and Cal/Val Coordination.....	8
2.4 Summary of observations for 2015, Week 06 (02/02-08/02)	9
3. ROUTINE QUALITY CONTROL	10
3.1 Gaps analysis.....	10
3.2 Orbit and Attitude Products	10
3.2.1 Swarm A	11
3.2.2 Swarm B	14
3.2.3 Swarm C	18
3.3 Magnetic Products	23
3.3.2 Swarm B	28
3.3.3 Swarm C	32
3.3.4 Summary of TCF behaviour for the three S/C	32
4. ON-DEMAND ANALYSIS.....	34





AMENDMENT POLICY

This document shall be amended by releasing a new edition of the document in its entirety. The Amendment Record Sheet below records the history and issue status of this document.

AMENDMENT RECORD SHEET

ISSUE	DATE	REASON
1.0	12 Feb 2015	First issue



1. INTRODUCTION

This document refers to the activities carried out in the framework of the Sensor Performance, Products and Algorithms (SPPA) Office [RD.1], and as such it reports on work related to:

- Algorithms and Processors Development, Maintenance and Evolution: these include all algorithm and software evolution and maintenance aspects for the different components, for both the Operational processors (OP) and Prototypes processors (PP) of L1 and L2 chains.
- Performance Assessment: these include all Quality Control activities (on-line and offline, systematic or on-demand), for the applicable product levels.
- System Calibration: these include the activities related to calibration, from sensor to system level. They also include aspects like cross calibration and handling of external calibration sources.
- Product validation: these include definition and maintenance of product validation plans.
- End-to-end Sensor Dataset Performance: these include activities related to the organisation and coordination of Quality Working Groups and all aspects of the Experimental platform. It also covers the product baseline, coordination and handling of external communities, and all aspects of ADF handling (both for the operational processors and for the prototypes).

This weekly report constitutes a work in progress throughout the mission life time, and new parts and complements will be added while the consolidation of knowledge on Swarm data and instruments will progress.

Section 2.1 always gives an overview of the general quality status of the mission instruments and products, while the main observations of the week are summarized in Section 2.4.

The document also includes information on data quality for the three Swarm spacecraft, inferred from automated HTML quality reports which are produced on daily basis for each product. Please contact the IDEAS+ Swarm team if interested in accessing the reports via web or FTP (all details about interfaces and folder structure available on [RD.2]). Such quality reports represent the core of the Routine Quality Control (Chapter 3). A description of the implemented quality checks is given in [RD.3], and references therein.

Basing on specific findings of the routine quality control, or on-demand from other entities (i.e. Swarm PDGS, FOS, Mission Management, Post-Launch Support Office, Expert Support Laboratories, Quality Working Groups, user community), anomalies can be triggered and preliminary characterisations and investigations of such anomalies are given in Chapter 4. The anomalies documented in the Weekly Reports are tracked in the following way:

1. If triggered by ESA Eohelp or within the Service: IDEAS+ action and ticketing system (<http://requests-sppa.serco.it/RT3/index.html>).
2. If triggered by IDEAS+ Swarm team or other entities:
 - 2a. If the observation/analysis leads to an anomaly to be addressed to the processor provider (GMV): SPR on EO ARTS (<https://arts.eo.esa.int>), **SWL1L2DB** project.



2.b. If the observation/analysis does not lead to an anomaly or the investigation shall be escalated to other entities (PLSO/industry, ESL, PDGS): Action tracked on EO ARTS, **SW-IDEAS** project, then addressed to the proper tracking system if needed (e.g. JIRA for ESLs, SW-CP-AR project on EO ARTS for PDGS)

Information on Level 1B Swarm products can be found in [RD.4].

1.1 Current Operational configuration of monitored data:

- Processors Version: L1BOP 3.11p3, L2-Cat2 1.12
- L0 input products baseline: 02
- L1B baseline: 03 (for definitions and description of the data baseline concept see <https://earth.esa.int/web/guest/missions/esa-operational-eo-missions/swarm/data-access/product-baseline-definition>)
- Level 2 – Cat 2 baseline: 01
- Input auxiliary files baseline: CCDB 0009, ADF 0101
- MPPF-CVQ v.2.12p1

1.2 Reference documents

The following is a list of documents with a direct bearing on the content of this report. Where referenced in the text, these are identified as RD.n, where 'n' is the number in the list below:

- [RD.1] Sensor Performance, Products and Algorithms (SPPA), PGSI-GSOP-EOPG-TN-05-0025. Version 2.3.
- [RD.2] Swarm PDGS External DMC Interface Control Document, SW-ID-DS-GS-0001, Issue 3.2.
- [RD.3] Swarm MPPF-CVQ Monitoring Baseline Document, ST-ESA-SWARM-MBD-0001, Issue 1.7.
- [RD.4] Swarm Level 1B Product Definition, SW-RS-DSC-SY-0007, Issue 5.13.
- [RD.5] Swarm IDEAS Configuration Management Plan, IDEAS-SER-MGT-PLN-1081 v0.14.
- [RD.6] Swarm Quality Control Project Plan, IDEAS-SER-MGT-PLN-1071
- [RD.7] SW_L1BOP_status_20141124_MoM
- [RD.8] Planned Updates for Level 1b, SW-PL-DTU-GS-008, Rev: 1dC.
- [RD.9] IDEAS+ Swarm Weekly Report: 25/08/2014 – 31/08/2014, IDEAS+-SER-OQC-REP-2071_SPPA_SwarmWeeklyReport_20140825_20140831.pdf (ref. for SWL1L2DB-9)
- [RD.10] IDEAS+ Swarm Weekly Report: 29/09/2014 – 05/10/2014, IDEAS+-SER-OQC-REP-2071_SPPA_SwarmWeeklyReport_20140929_20141005.pdf (ref. for SW-IDEAS-34)
- [RD.11] IDEAS+ Swarm Weekly Report: 06/10/2014 – 12/10/2014, IDEAS+-SER-OQC-REP-2071_SPPA_SwarmWeeklyReport_20141006_20141012.pdf (ref. for SW-IDEAS-36)
- [RD.12] IDEAS+ Swarm Weekly Report: 20/10/2014 – 26/10/2014, IDEAS+-SER-OQC-REP-2071_SPPA_SwarmWeeklyReport_20141020_20141026.pdf (ref. for SW-IDEAS-40, GPS sync loss)
- [RD.13] IDEAS+ Swarm Weekly Report: 15/09/2014 – 21/09/2014, IDEAS+-SER-OQC-REP-2071_SPPA_SwarmWeeklyReport_20140915_20140921.pdf (ref. for SW-IDEAS-27)





2. SUMMARY OF THE OBSERVATIONS

2.1 General status of Swarm instruments and Level 1B products quality

No news to report.

2.2 Plan for operational processor updates

L1BOP 3.12 and L2-Cat2OP 1.13 have been delivered to PDGS the 28th of November. Verification and integration tests will take place in the next weeks, before the final deployment of the processors in operation in January.

After the delivery of L1BOP 3.13, GMV realized a bug was left in the GPSx_RO_1B products computation that led Napeos end with errors, even though not blocking for the MOD generation. For that reason a L1BOP 3.14 has been delivered past week. The non regression tests have been completed and the deployment in operations is foreseen for CW 7 (16-20/02).

2.3 Quality Working Group and Cal/Val Coordination

Coordination is in place for organizing the 6th Swarm Data Quality Workshop in Paris (hosted by IPGP) in late September 2015.

Following the QWG recommendations in Potsdam and the scientists need in view of the IUGG conference in June, the preliminary plasma dataset will be released end of January 2015.

According to the last coordination meeting within the MAGNET QWG (22/01/2015) the following decisions have been taken:

- With the data provided by DTU/ESL, further analysis can be performed by industry (ADS, DTU-MI, other scientific groups (e.g. Richard Marchand and Stephan Buchert on plasma induced fields), and of course by ESA. The agreement is - as always - that results will be shared with all others on the Task Force.

- DTU/ESL will further refine the Lesur-Tøffner-Clausen model parametrisation and share a final description of the process (input data, model description, output results and tests) (by mid February).

- In parallel, GFZ will distribute the Lühr-Michaelis results, and a number of people (e.g. Malcolm Dunlop, Yulia Bogdanova, Arnaud Chulliat, Patrick Alken) will further support the analysis of these datasets. (by mid February).

- The PDGS will generate the currently VFM missing data on Charlie due to the ASM failure (by end February).

- DTU/ESL will share the final set of corrected data by early March. These corrected data will also contain the dBsun correction, providing the users the possibility to access to uncorrected data.

- The corrected data will be distributed by ESA to all Swarm users (by early April and no later than 20th April). The correction will also be implemented in the OP. Until this is fully validated, it is agreed that the operational processing will continue as nominal without the correction.



- Next Task Force meeting: **9-10 April**. The meeting will be held in ESTEC.

2.4 Summary of observations for 2015, Week 06 (02/02-08/02)

During the monitored week the following events have been found and investigated:

1. **Strange features observed at times in the MOD-GPSNAV solution difference:** again we often notice a marked “spiky” behaviour, with deviations from the average which are not normal spikes but lasts for several seconds if not minutes (**SW-IDEAS-34**, [RD.10]).
2. **Attitudes rejected for few seconds** on S/C C, due to simultaneous occurrence of BBO and Invalid measurements on the three cameras (**SW-IDEAS-52**).
3. **A decrease of the TCF Non orthogonality Y component** observed for S/C A in the period Dec 2014 – Jan 2015 (**SW-IDEAS-53**).



3. ROUTINE QUALITY CONTROL

3.1 Gaps analysis

- **Magnetic production lost on S/C C for the whole week**, because of the ASM switched off.

3.2 Orbit and Attitude Products

The following events have to be reported:

Observation ID	Description	Affected parameter	Sect. of Obs. Description	Sect. of Obs. analysis
SW-IDEAS-34	OBS_ROUTINE: large number of spiky features observed in the NAV-MOD difference	Orbits (position and velocity)	3.2.2.1	[RD.10]
SW-IDEAS-52	OBS_ROUTINE: week 02-08/02/2015 STR S/C C out of range.	STRCSCI_1A STRCATT_1B	3.2.3.2	3.2.3.2

Table 1: list of events related to attitude and orbit products to be reported in the monitoring for 2015, Week 06: 02/02 - 08/02.

The relevant parameters that have been monitored are:

- Position difference between calculated Medium Accuracy orbits (**MODx_SC_1B**) and on-board solution (**GPSxNAV_0**). Threshold values for such differences have not been assessed yet: we have just monitored the average values and maximum variations around the week, and reported in tables in the sections below, along with some example from the HTML daily reports. For the time being we evaluated an anomaly should be raised if one (or more) of the following conditions occurs:
 - o The **average difference** on a given day exceeds the position accuracy requirement for the mission (1.5 m),
 - o The variability around the average is quite high: **standard deviation** threshold has been arbitrarily chosen to be twice the position accuracy requirement for the mission (2-sigma = 3 m).
 - o At least 4-5 spikes are observed on a given day, exceeding +/- 50 m.
- Visual inspection of Star Tracker characterisation flags (**STRxATT_1B**)
- Deviation of the quaternion norm from unity (deviation threshold = +/- 10⁻⁹)
- Visual inspection of Euler Angles derived from quaternions.



3.2.1 Swarm A

3.2.1.1 Position statistics

In Table 2 one can see the statistics of the differences between MOD and on-board solution positions. In the third column the maximum differences (maximum negative and maximum positive) are reported with, in parentheses, the ITRF component affected by such difference. The maximum standard deviation is in the fourth column: it usually refers to the Z component which is always the most disturbed; in case another component is most affected, it will be specified in parentheses.

Swarm A, 02/02 – 08/02, Position difference				
Day	Average Difference (m)	Maximum difference (m)	Standard deviation (m)	Notes
02/02	0.22	-17 (X), 9.4 (Z)	1.7	Isolated spike on X comp.
03/02	0.2	-11, 9.6 (Z)	1.5	SW-IDEAS-34 [RD.10]
04/02	0.07	-12.5, 7 (Z)	1.3	SW-IDEAS-34 [RD.10]
05/02	0.02	-7.6, 11.6 (Z)	1.4	
06/02	0.17	-13.8, 6 (Z)	1.3	Isolated spike on Z comp.
07/02	0.17	-13.6, 9.5 (Z)	1.5	SW-IDEAS-34 [RD.10]
08/02	0.08	-9.2, 7.2 (Z)	1.3	

Table 2: Swarm A, difference between MOD and on-board solution positions.

Below some plot example follows of such differences taken at the beginning of the week (02/02, Figure 1), in the middle (05/02, Figure 2) and at the end (08/02, Figure 3). From top to bottom the plots show: the S/C position determined from the MOD calculation, the S/C position determined on-board, the difference between the two. The values are given in Km.

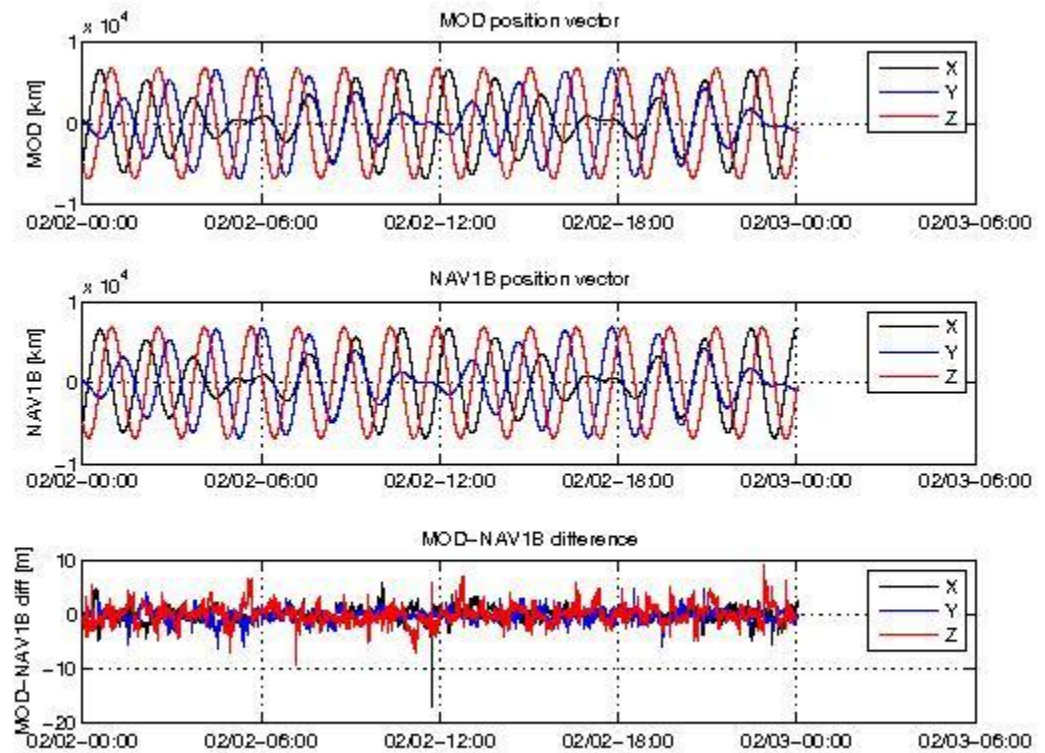


Figure 1: Difference MOD-GPSNAV, sc A, 02/02/2015. From top to bottom: the S/C position determined from the MOD calculation, the S/C position determined on-board, the difference between the two.

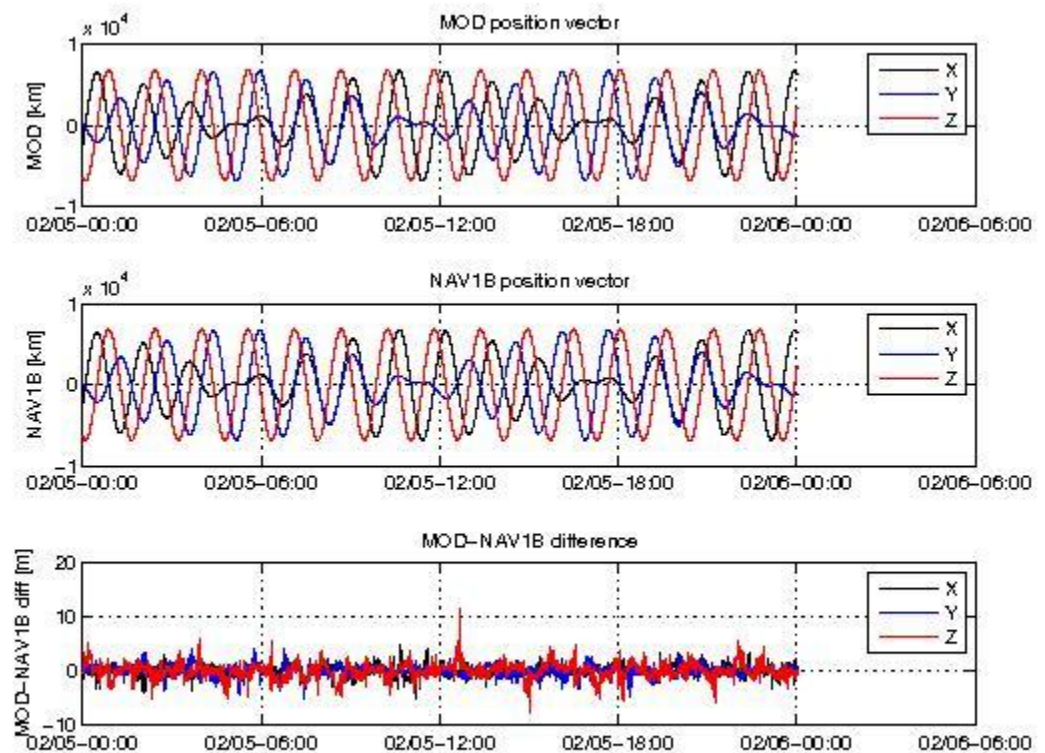


Figure 2: Difference MOD-GPSNAV, sc A, 05/02/2015. From top to bottom: the S/C position determined from the MOD calculation, the S/C position determined on-board, the difference between the two.

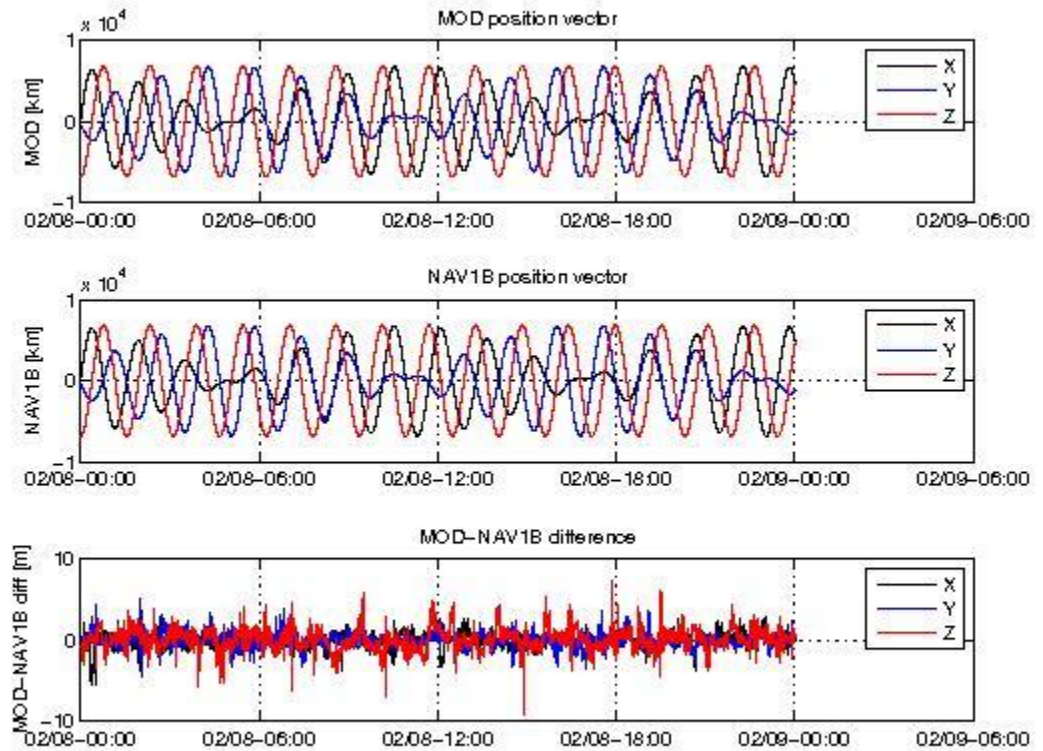


Figure 3: Difference MOD-GPSNAV, sc A, 08/02/2015. From top to bottom: the S/C position determined from the MOD calculation, the S/C position determined on-board, the difference between the two.

3.2.1.2 Attitude observations

Nothing to report.

3.2.2 Swarm B

3.2.2.1 Position Statistics

In Table 3 one can see the statistics of the differences between MOD and on-board solution positions. In the third column the maximum differences (maximum negative and maximum positive) are reported with, in parentheses, the ITRF component affected by such difference. The maximum standard deviation is in the fourth column: it usually refers to the Z component which is always the most disturbed; in case another component is most affected, it will be specified in parentheses.



Swarm B, 02/02 - 08/02, Position difference				
Day	Average Difference (m)	Maximum difference (m)	Standard Deviation (m)	Notes
02/02	0.13	-9 (X), 9 (Z)	1.6	SW-IDEAS-34 [RD.10]
03/02	0.16	-5.4, 7.4 (Z)	1.4	
04/02	0.08	-14.7 (Z), 5.5 (Y)	1.3	Isolated spike on Z comp.
05/02	0.07	-9.5, 8 (Z)	1.5	SW-IDEAS-34 [RD.10]
06/02	0.08	-8 (X), 7.5 (Z)	1.4	SW-IDEAS-34 [RD.10]
07/02	0.11	+/- 9 (Z)	1.5	SW-IDEAS-34 [RD.10]
08/02	0.16	-9.5, 6 (Z)	1.4	SW-IDEAS-34 [RD.10]

Table 3: Swarm B, difference between MOD and on-board solution positions.

Below some plot example follows of such differences taken at the beginning of the week (02/02, Figure 4), in the middle (05/02, Figure 5), and at end of the week (08/02, Figure 6). From top to bottom the plots show: the S/C position determined from the MOD calculation, the S/C position determined on-board, the difference between the two. The values are given in Km.

In Figure 4 examples of SW-IDEAS-34 ([RD.10]) anomaly is shown (red-circled areas): the MOD-NAV solution difference departs from the average value taking higher/lower values for several minutes.

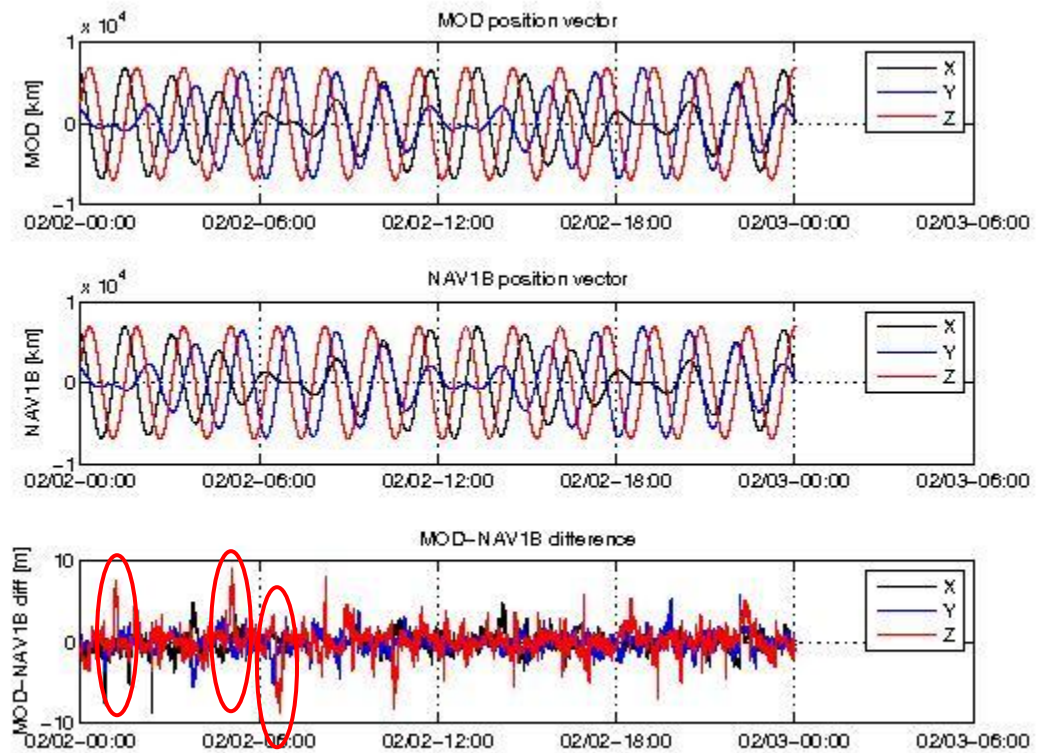


Figure 4: Difference MOD-GPSNAV, sc B, 02/02/2015. From top to bottom: the S/C position determined from the MOD calculation, the S/C position determined on-board, the difference between the two. The red-circled areas evidence a time interval characterized by SW-IDEAS-34 ([RD.10]) anomaly occurrence.

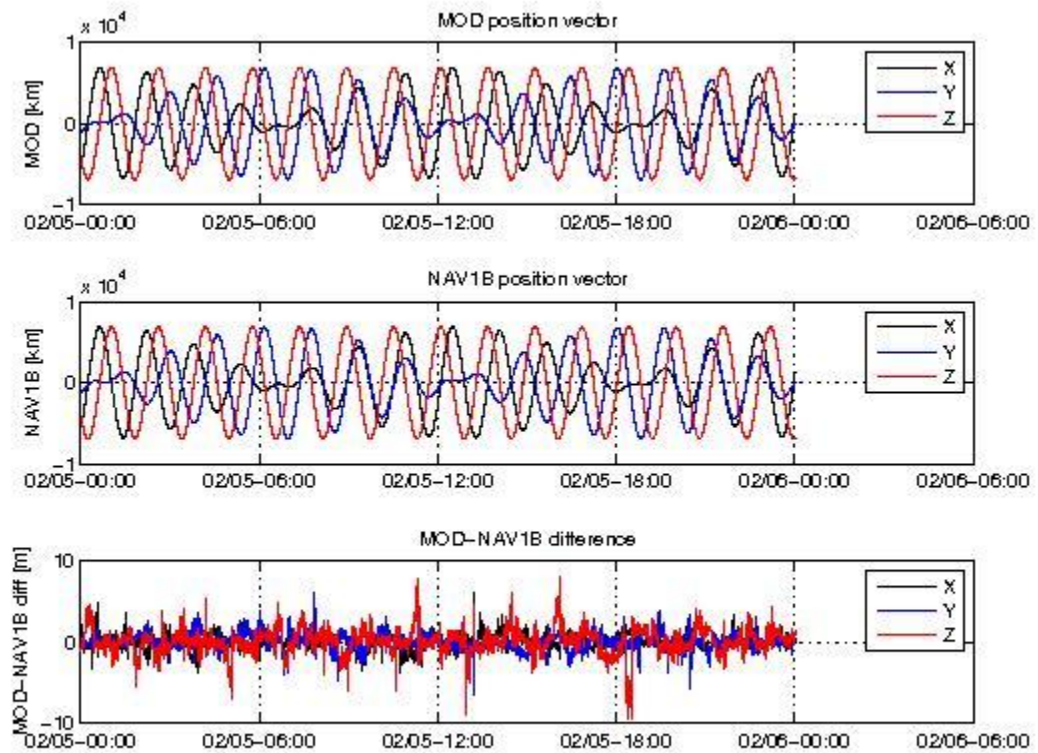


Figure 5: Difference MOD-GPSNAV, sc B, 05/02/2015. From top to bottom: the S/C position determined from the MOD calculation, the S/C position determined on-board, the difference between the two.

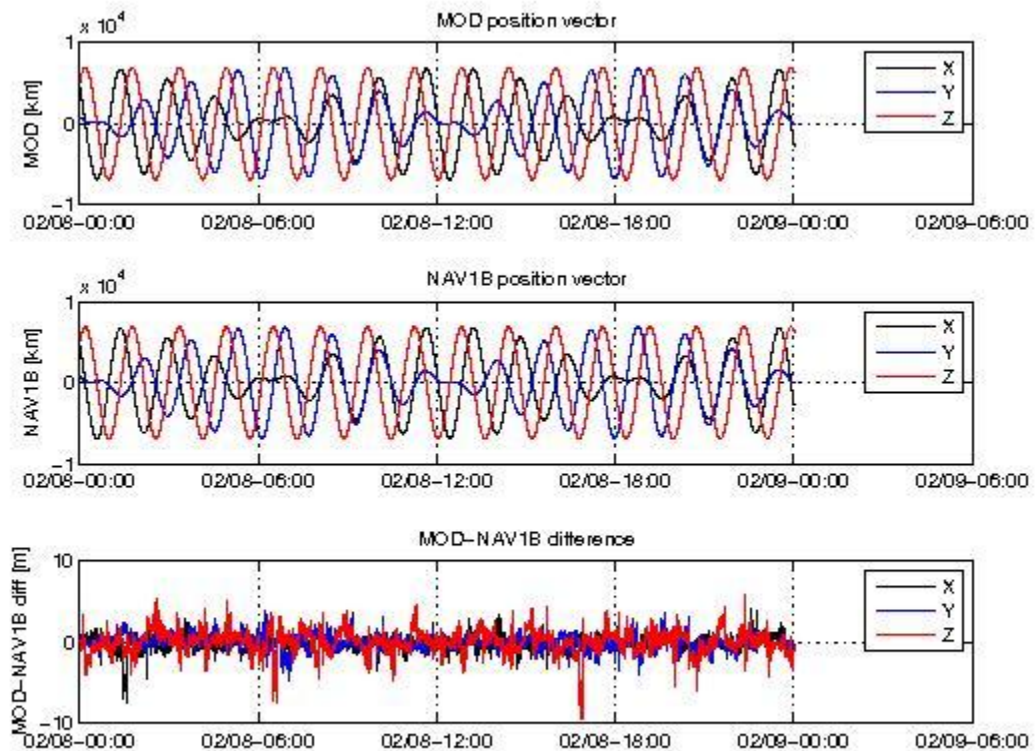


Figure 6: Difference MOD-GPSNAV, sc B, 08/02/2015. From top to bottom: the S/C position determined from the MOD calculation, the S/C position determined on-board, the difference between the two.

3.2.2.2 Attitude observations

Nothing to report.

3.2.3 Swarm C

3.2.3.1 Position Statistics

In Table 4 one can see the statistics of the differences between MOD and on-board solution positions. In the third column the maximum differences (maximum negative and maximum positive) are reported with, in parentheses, the ITRF component affected by such difference. The maximum standard deviation is in the fourth column: it usually refers to the Z component which is always the most disturbed; in case another component is most affected, it will be specified in parentheses.



Swarm C, 02/02 - 08/02, Position difference				
Day	Average Difference (m)	Maximum difference (m)	Standard Deviation (m)	Notes
02/02	0.18	-7.5, 9 (Z)	1.5	SW-IDEAS-34 [RD.10]
03/02	0.13	-11.4, 13.4 (Z)	1.3	Isolated spikes on Z comp.
04/02	0.11	-7 (Y), 14 (Z)	1.2	Isolated spikes on Z comp.
05/02	0.04	-9.3, 10 (Z)	1.4	
06/02	0.13	+/- 6 (Z)	1.3	
07/02	0.18	+/- 7 (Z)	1.2	
08/02	0.16	+/- 8 (Z)	1.3	

Table 4: Swarm C, difference between MOD and on-board solution positions.

Below some plot example of such differences follows, taken at the beginning of the week (02/02,

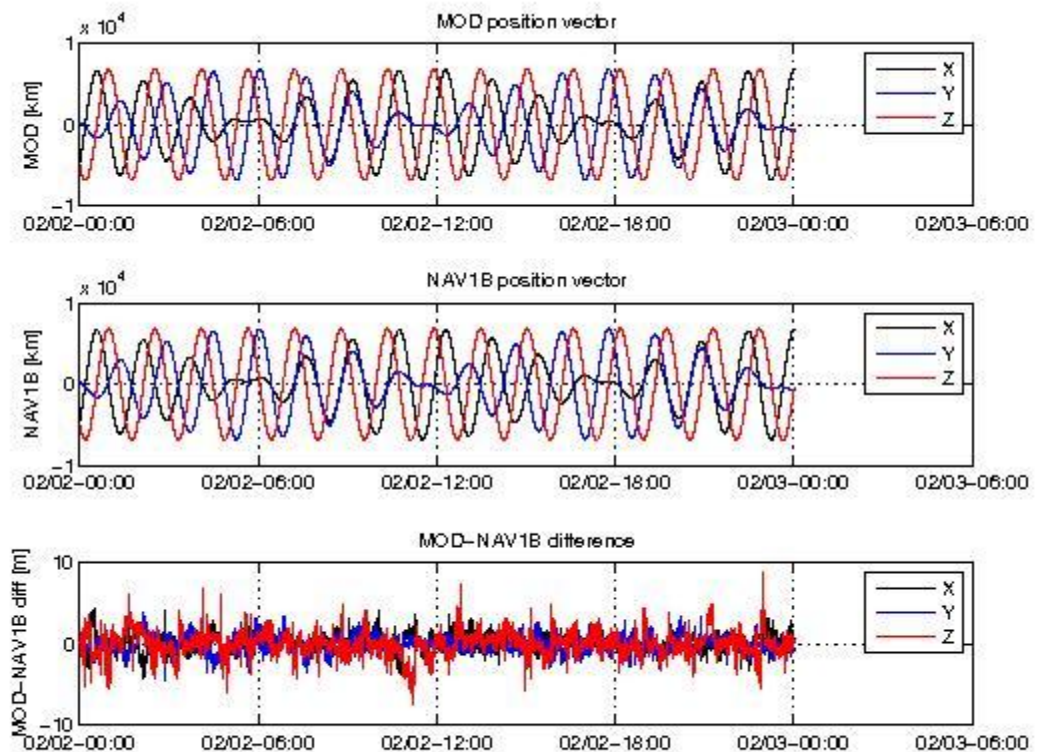


Figure 7), in the middle (05/02, Figure 8) and at the end (08/02, Figure 9). From top to bottom the plots show: the S/C position determined from the MOD calculation, the S/C position determined on-board, the difference between the two. The values are given in Km.

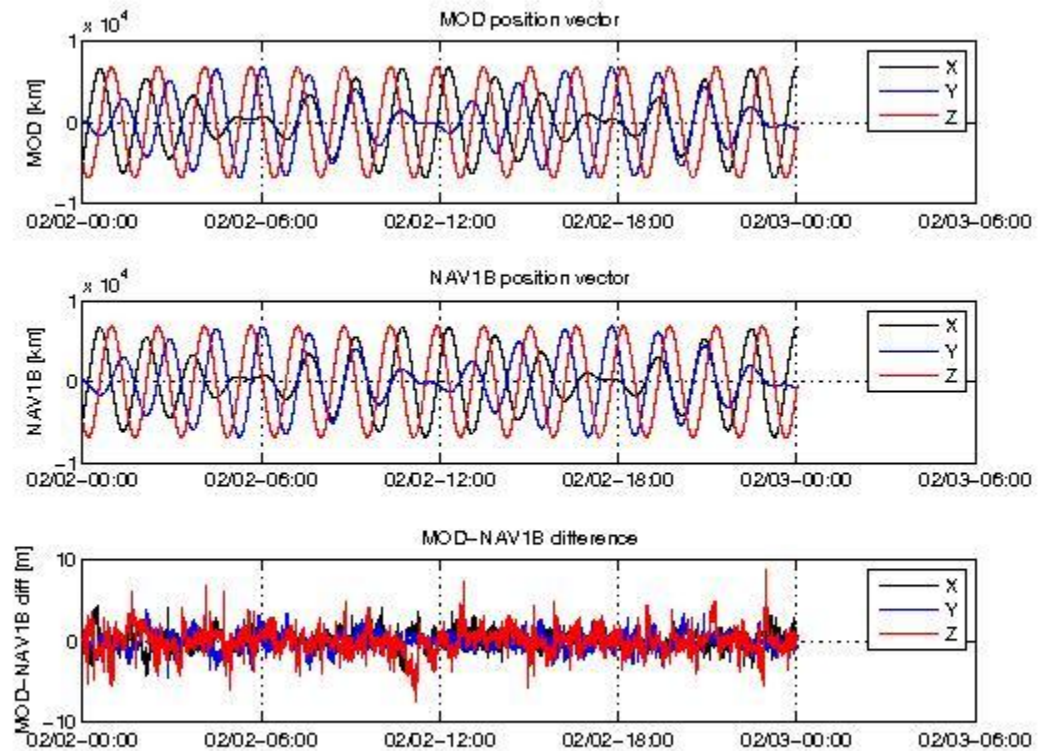


Figure 7: Difference MOD-GPSNAV, sc C, 02/02/2015. From top to bottom: the S/C position determined from the MOD calculation, the S/C position determined on-board, the difference between the two.

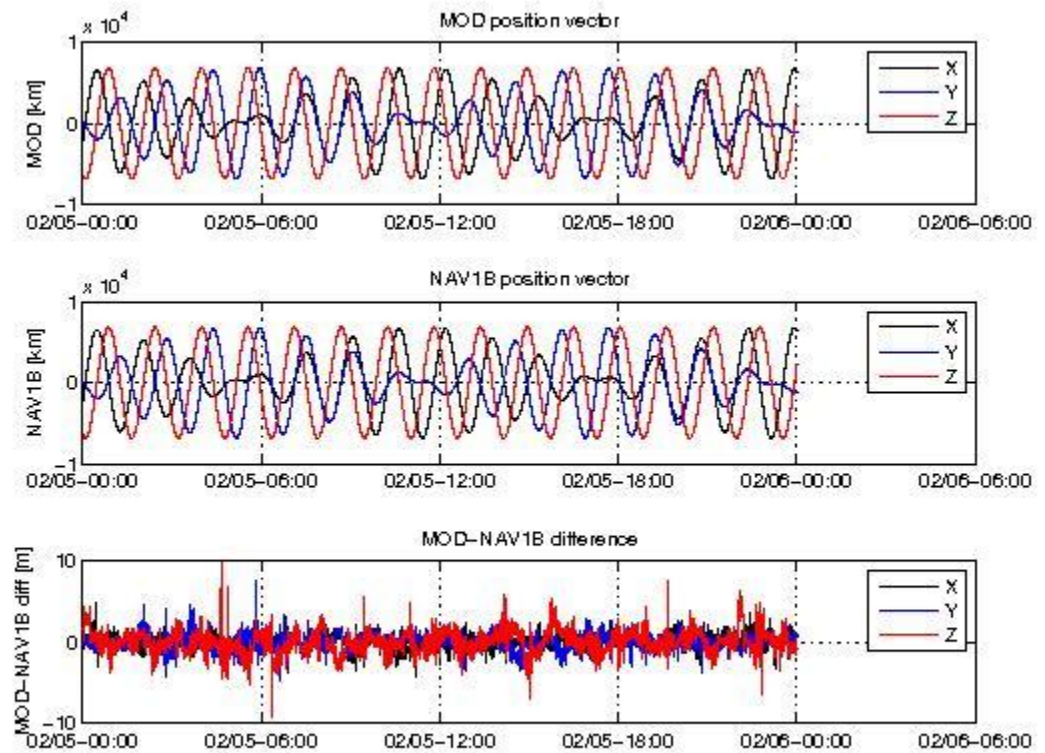


Figure 8: Difference MOD-GPSNAV, sc C, 05/02/2015. From top to bottom: the S/C position determined from the MOD calculation, the S/C position determined on-board, the difference between the two.

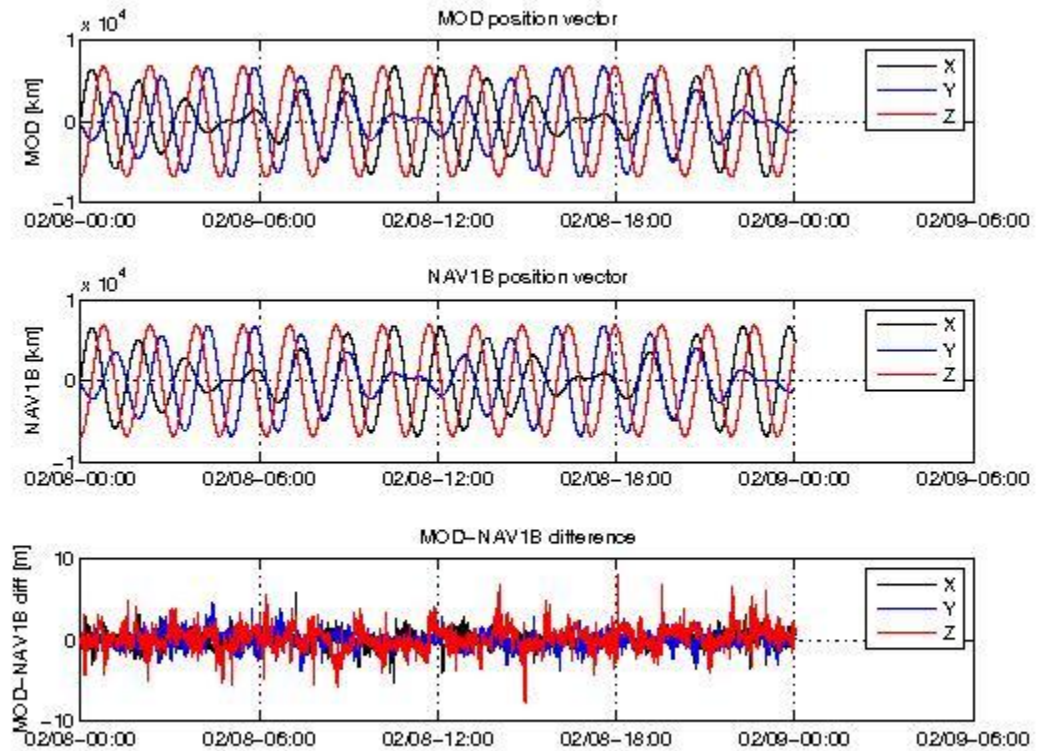


Figure 9: Difference MOD-GPSNAV, sc C, 08/02/2015. From top to bottom: the S/C position determined from the MOD calculation, the S/C position determined on-board, the difference between the two.

3.2.3.2 Attitude observations

- **SW-IDEAS-52**

Affected products:

SW_OPER_STRCATT_1B_20150105T000000_20150105T235959_0302

6 seconds out of range (Flags_q=255, no attitude available). See details in Table 5 below.

Start Out-of-range	Stop Out-of-range	Duration (s)
05FEB2015 23:17:38	05FEB2015 23:17:43	6

Table 5: Attitudes out-of-range, S/C B, 2015, week 06.

The cause of such rejected attitudes is the simultaneous occurrence of BBOs on cameras 2 and 3, and invalid measurements for camera 1 in the specified interval.



3.3 Magnetic Products

For the magnetic products the weekly monitoring consists in:

- Visual inspection of daily time series of magnetic field intensity F , B_{NEC} and B_{VFM} . Looking for gaps (or zero values in case of **MAGx_LR_1B** products), out-of-threshold values (i.e. exceeding +/- 60000 nT), and other strange features.
- Monitoring of the **VFM-ASM known anomaly**: visual inspection of $|B_{NEC}| - F$ and recording of daily maximum variations. If +/- 5 nT are exceeded on a given day, an alert is raised.
- TCF.VFM parameters monitoring (VFM calibration parameters): series of biases, scales, non-orthogonality factors and RMS. **This check is performed on monthly basis.**

SW-IDEAS-27 [RD.13]: Due to moderate geomagnetic activity throughout the week, we observe at time high level of noise in the high frequency region of the spectra. In particular, day 02/02 is very disturbed, with Kp getting close to 5, and AE above 1000 nT for most of the day: the noise superimposed on the spectra is therefore very strong.

3.3.1.1 Magnetic time series visual inspection

An example of representative magnetic field time series for S/C A can be seen in Figure 10 (08/02/2015).

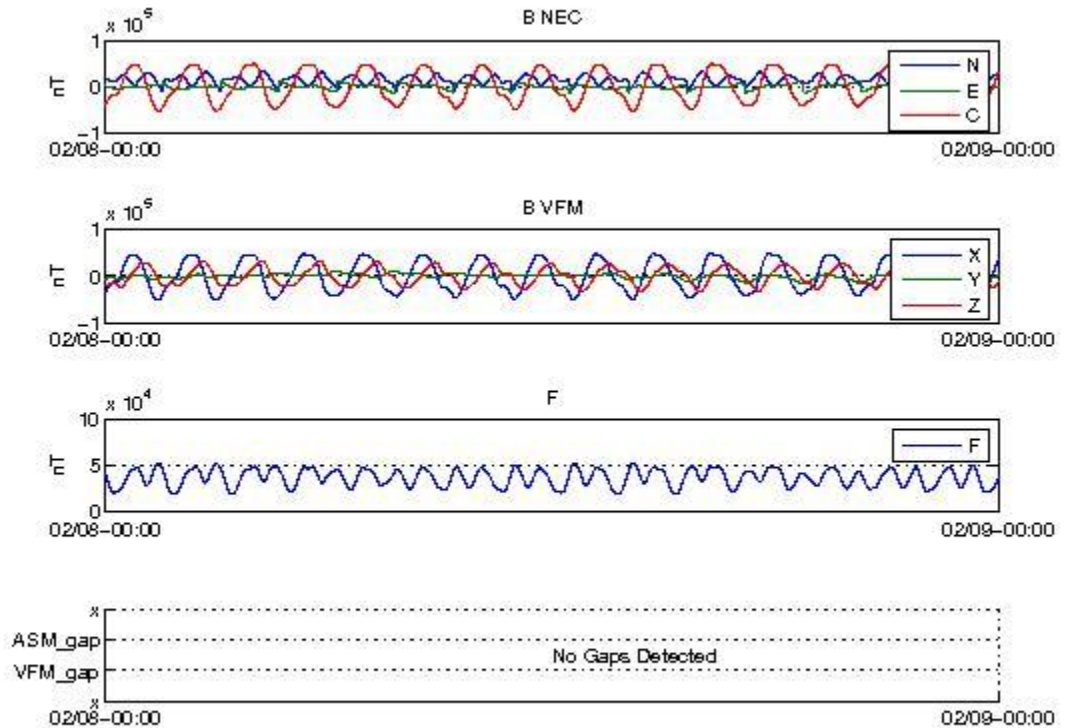


Figure 10: Time series of the geomagnetic field, for 08/02/2015, S/C A. From top to bottom: magnetic field components in NEC reference frame, magnetic field components in the VFM reference frame, magnetic field intensity (F) from ASM, and location of gaps (if any).

3.3.1.2 VFM-ASM anomaly

The daily peak-to-peak difference around the week is, on average: [-2.5, 3.5] nT, with occasional spikes up to 7 nT.

Below two example plots of such differences follows: taken at the beginning of the week 02/02 (Figure 11) and at the end of the week 08/02, (Figure 12). From top to bottom the plots show: The VFM module, the ASM module, the difference ASM-VFM.

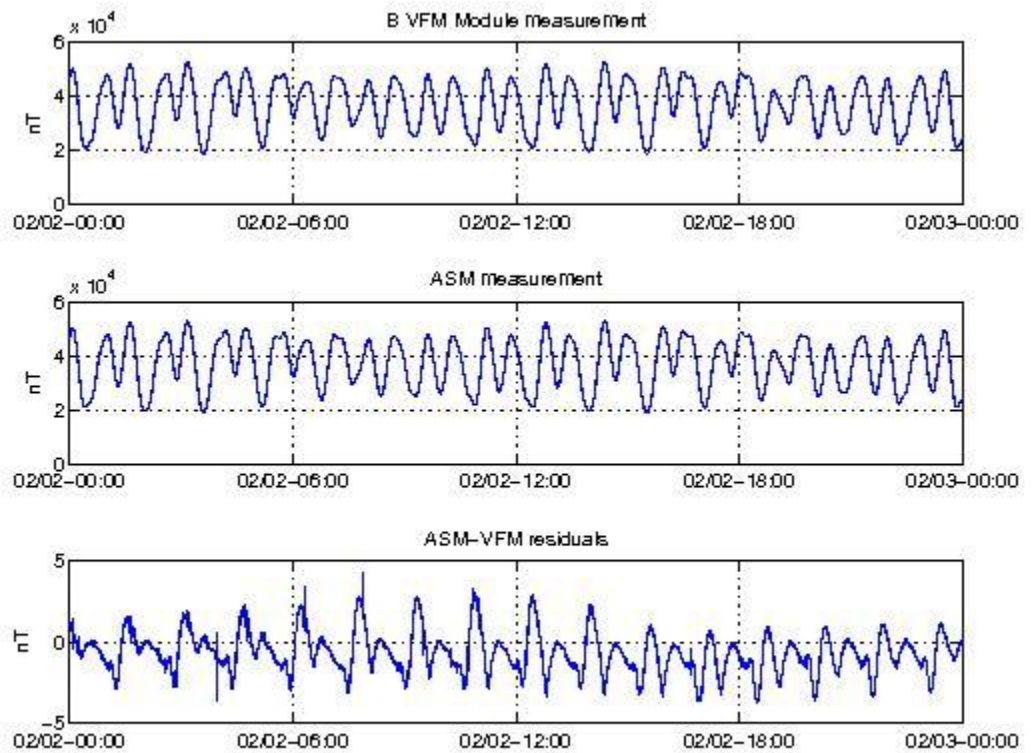


Figure 11: VFM module, ASM module and ASM-VFM residuals for S/C A, 02/02/2015.

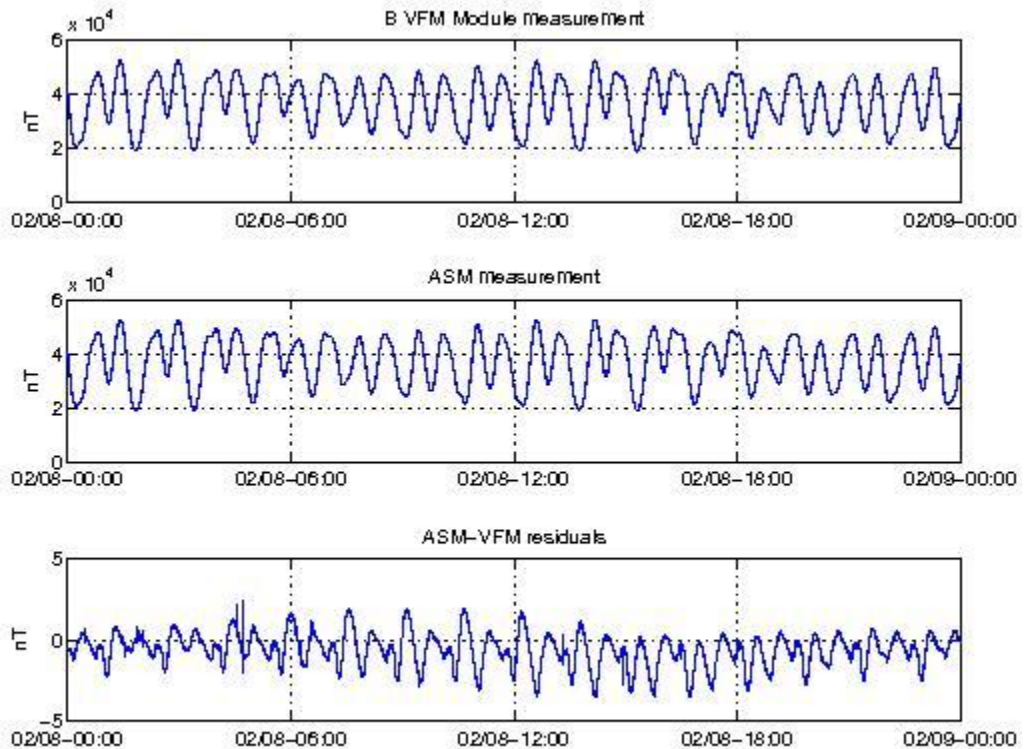


Figure 12: VFM module, ASM module and ASM-VFM residuals for S/C A, 08/02/2015.

3.3.1.3 TCF.VFM monitoring

In the following plots one can see the three groups of TCF VFM calibration parameters for Swarm A, for the period 23 November 2014 – 31 January 2015: Biases (**Error! Reference source not found.**), Scales (**Error! Reference source not found.**) and Non-orthogonalities (**Error! Reference source not found.**). Each group is actually a three-component vector in the compact detector coil frame. The biases are rather constant throughout the period (Figure 13); the Z scale factor has a slow decrease of about 0.002% (Figure 14); a remarkable decrease of the Y Non Orthogonality factor is observed, in two steps, of about 40% in two months (Figure 15) – **SW-IDEAS-53**. The issue has been submitted to the attention of the ESLs, but the conclusion is there is no reason to be alarmed, until variations do not exceed 1 mDeg.

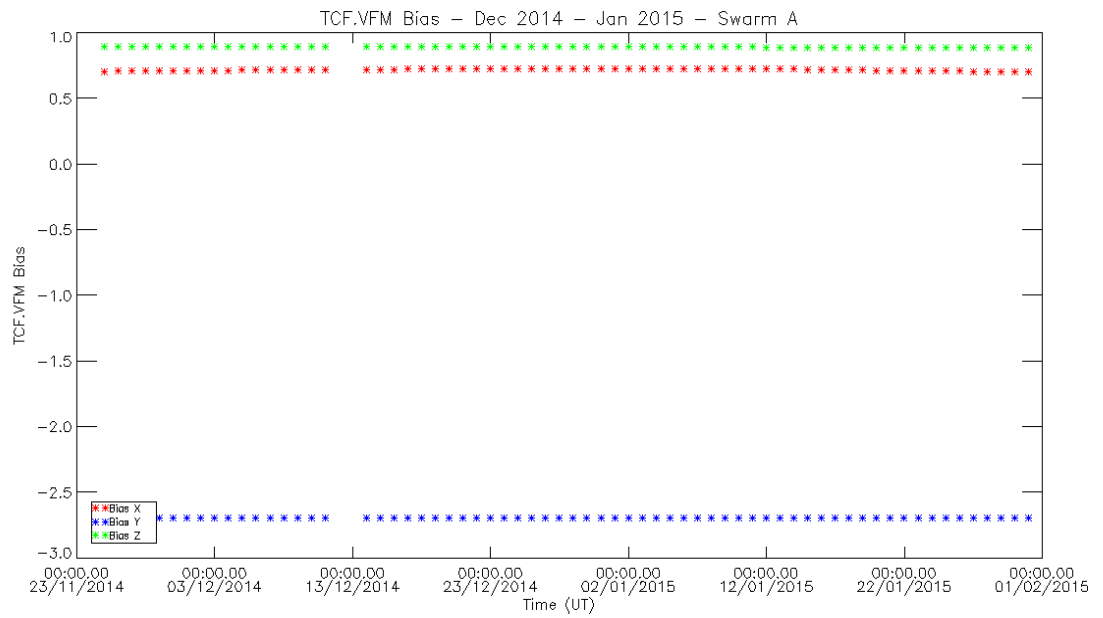


Figure 13: TCF.VFM Biases for S/C A, 23/11/2014 – 31/01/2015

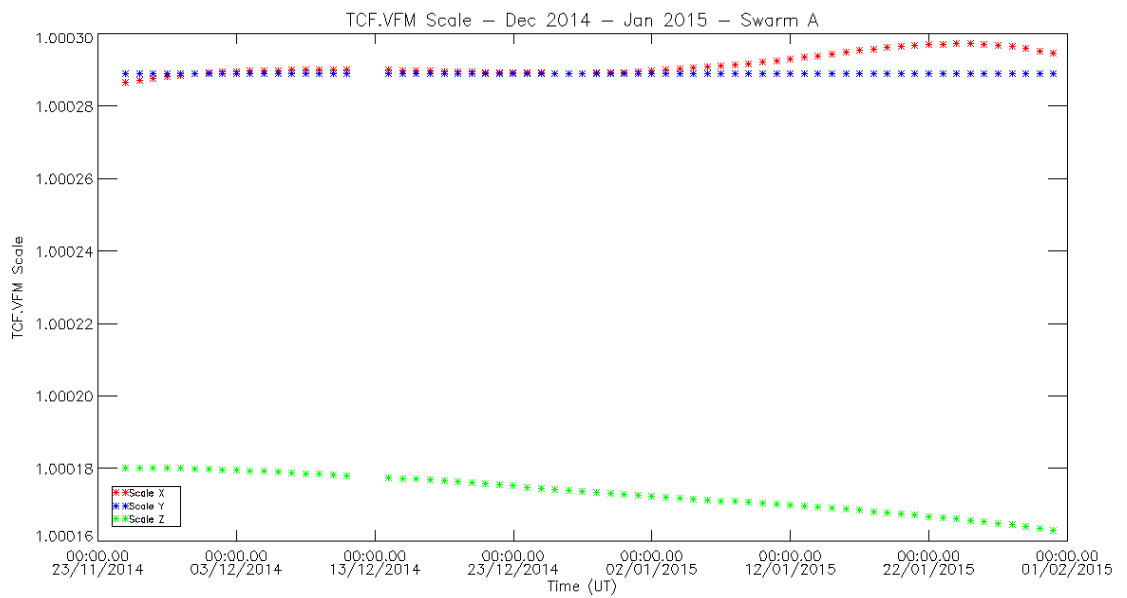


Figure 14: TCF.VFM Scales for S/C A, 23/11/2014 – 31/01/2015

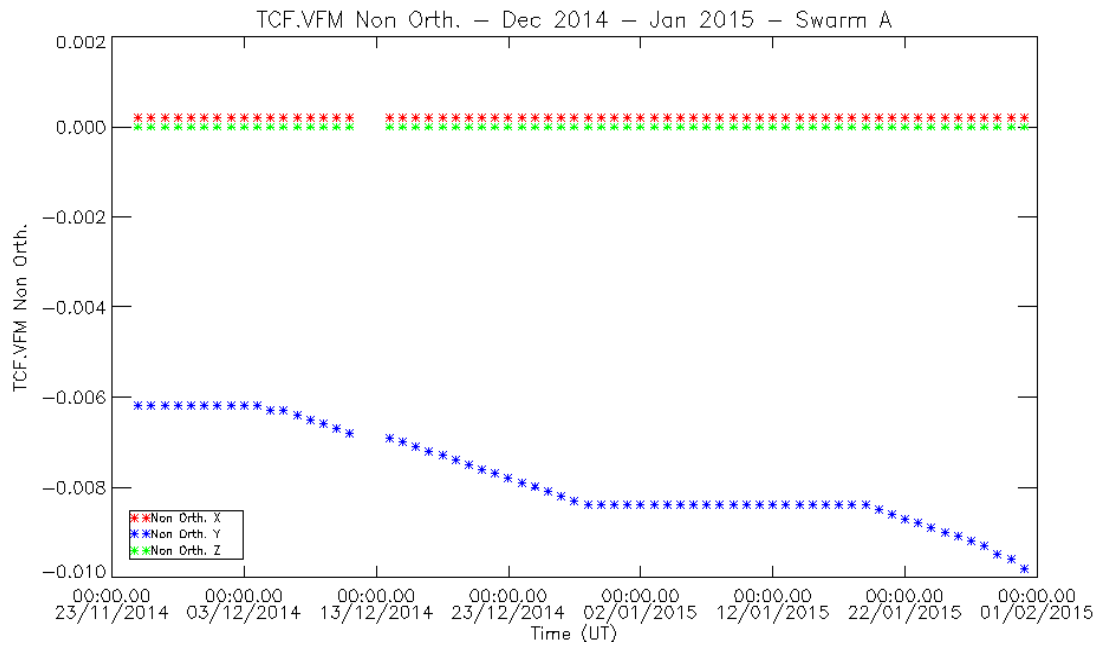


Figure 15: TCF.VFM Non Orthogonalities for S/C A, 23/11/2014 – 31/01/2015

3.3.2 Swarm B

3.3.2.1 Magnetic time series visual inspection

Nothing relevant to report. An example of representative magnetic field time series for S/C B (08/02/2015) can be seen in Figure 16 below.

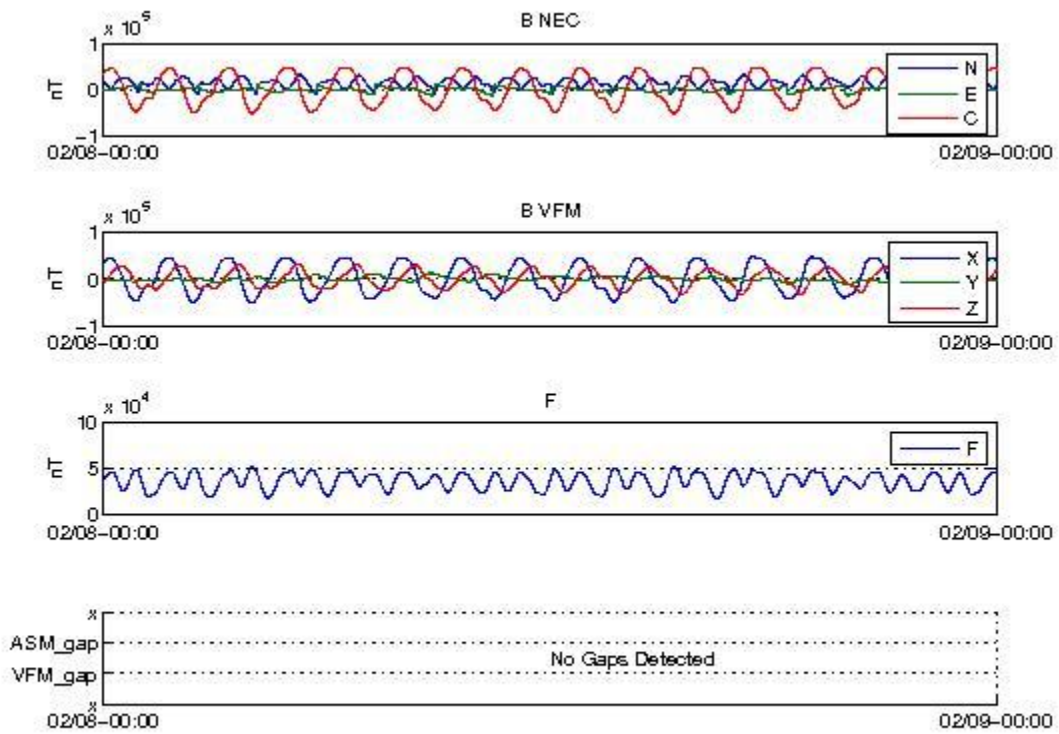


Figure 16: Time series of the geomagnetic field for 08/02/2015, S/C B. From top to bottom: magnetic field components in NEC reference frame, magnetic field components in the VFM reference frame, magnetic field intensity (F) from ASM, and location of gaps (if any).

3.3.2.2 VFM-ASM anomaly

The daily peak-to-peak difference around the week is, on average: [-1.5, 3.5] nT, with peaks of about 6 nT.

Below two example plots follows of such differences: 02/02 (Figure 17), and 08/02 (Figure 18). From top to bottom the plots show: The VFM module, the ASM module, the difference ASM-VFM.

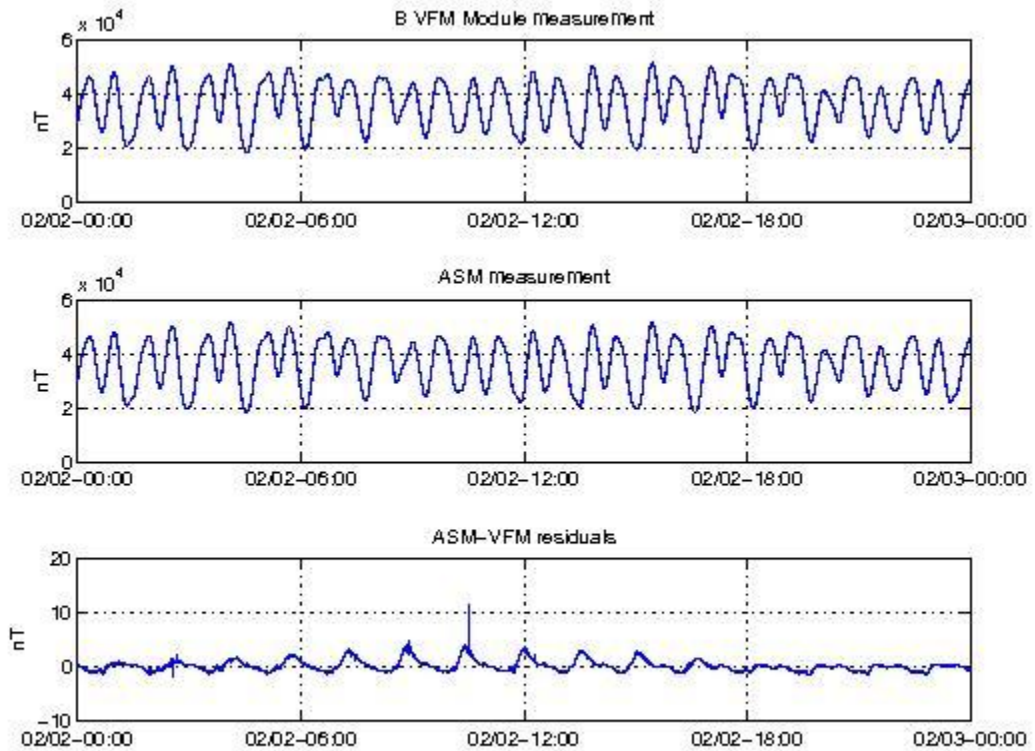


Figure 17: VFM module, ASM module and ASM-VFM residuals for S/C B, 02/02/2015

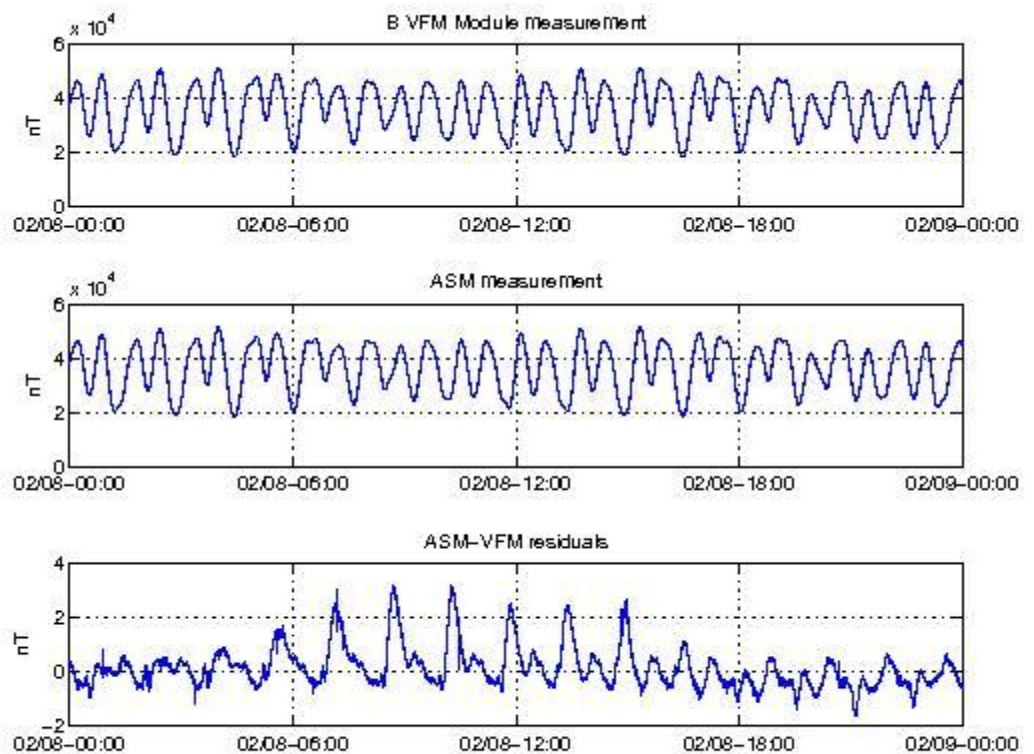




Figure 18: VFM module, ASM module and ASM-VFM residuals for S/C B, 08/02/2015.

3.3.2.3 TCF.VFM monitoring

In the following plots one can see the three groups of TCF VFM calibration parameters for Swarm B, for the period 23 November 2014 – 31 January 2015: Biases (Figure 19), Scales (Figure 20) and Non-orthogonalities (Figure 21). Each group is actually a three-component vector in the compact detector coil frame. All the parameters are rather constant and steady throughout the month, except for the Scale X and Z components (see Error! Reference source not found.), which show a slow rise up to mid December, then decrease again; overall, the maximum variation is about 0.002%.

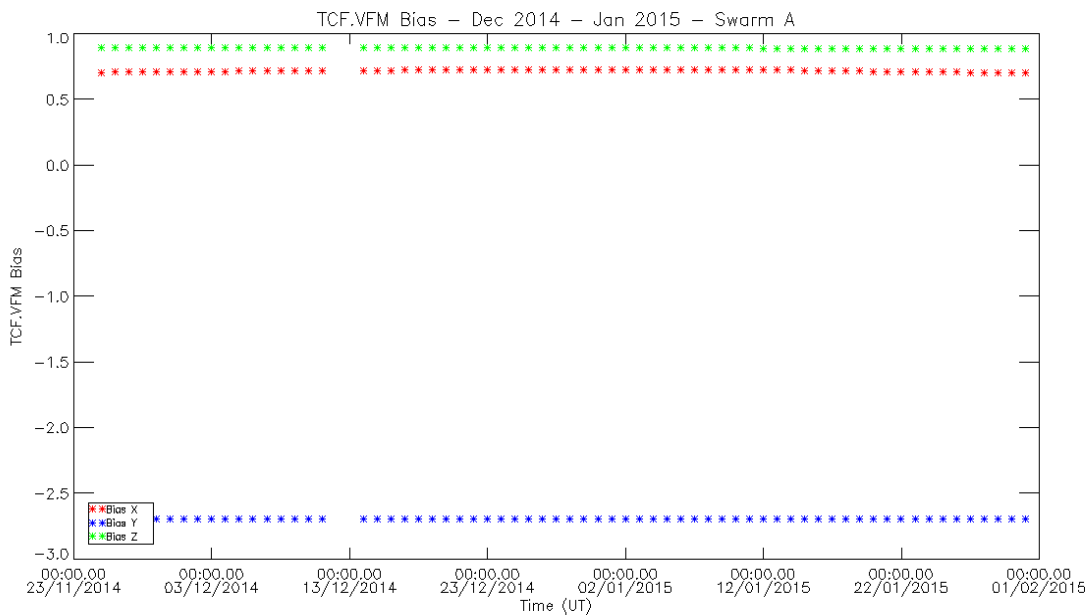


Figure 19: TCF.VFM Biases for S/C B, 23/11/2014 – 31/01/2015

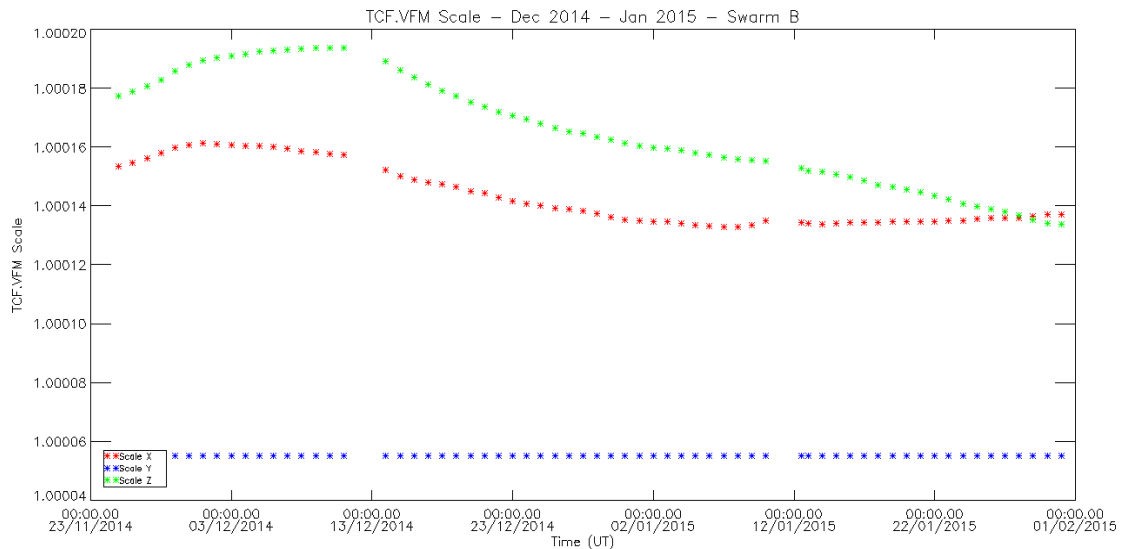


Figure 20: TCF.VFM Scales for S/C B, 23/11/2014 – 31/01/2015

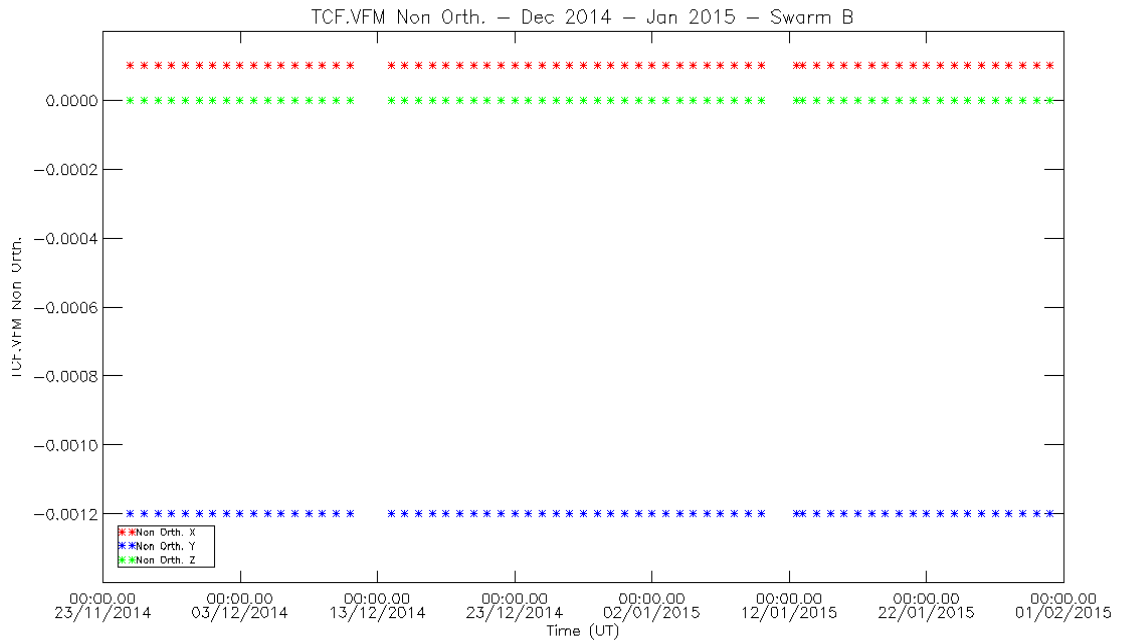


Figure 21: TCF.VFM Non Orthogonalities for S/C B, 23/11/2014 – 31/01/2015

3.3.3 Swarm C

3.3.3.1 Magnetic time series visual inspection

No data because ASM is still switched off

3.3.3.2 VFM-ASM anomaly

No data because ASM is still switched off

3.3.3.3 TCF.VFM monitoring

No data because ASM is still switched off

3.3.4 Summary of TCF behaviour for the three S/C

An important parameter which characterizes the quality of the TCF calculation is the weighted Root Mean Square (RMS) value of the residuals after the estimation. **Error! Reference source not found.** summarizes the RMS behavior for all S/C during the period 23 November 2014 - 31 January 2015 (Red curve = S/C A, blue curve = S/C B). An increase of about 40% is observed for S/C A, starting from about 02/01/2015.

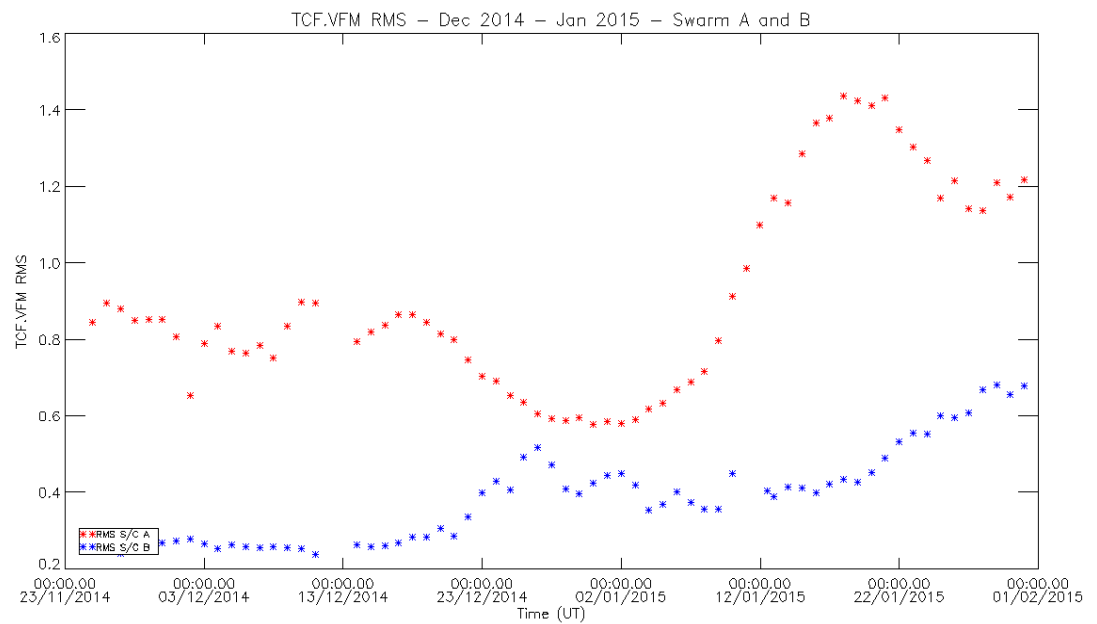


Figure 22: weighted RMS of the residuals after the TCF estimation, all S/C, 23 November 2014 – 31 January 2015.



4. ON-DEMAND ANALYSIS

Nothing to report.



End of Document