cesa




$\square$ RA2 level 1 Unexpected Gaps Innavailable
$\square R A 2$ level 1 Inventoried Production $\square$ RA2 Missian Plan

$\square$ RA2 level 2 Unexpected Gaps Unavailable
$\square R A 2$ level 2 Inventoried Production
RA2 Missian Plan

$\square$ clack_step
z velocity
y-position
sensing stop
proc_center
$19 / 06 / 2009$


| leap_ute |
| :--- |
| vectar_source |
| z position |
| phase |
| proc.time |
| filename | filename


|  | $3.8162 \times 10^{+}$ | $3.8164 \times 10^{+}$ | $3.8166 \times 10^{4}$ | $\begin{gathered} \text { Orits } \\ 3.8168 \times 10^{4} \end{gathered}$ | $3.8170 \times 10^{4}$ | $3.8172 \times 10^{4}$ | $3.8174 \times 10^{+}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| inventoried production | $1$ | $1$ |  |  |  |  |  |
| filename | \| | 1 | 1 | I | ${ }^{-}$ | 1 | 1 |
| proc_stage |  |  |  |  |  |  |  |
| acquisition_station |  |  |  |  |  |  |  |
| prooceenter |  |  |  |  |  |  |  |
| proctime |  |  |  |  |  |  |  |
| software_ver | 1 |  |  |  |  |  |  |
| sensing_stort | 1 |  |  |  |  |  |  |
| sensing stop |  |  |  |  |  |  |  |
| phase |  |  |  |  |  |  |  |
| state_vector_time |  |  |  |  |  |  |  |
| $x$-position |  |  |  |  | I |  |  |
| y-position |  |  |  |  |  |  |  |
| $z$ position |  |  |  |  |  |  |  |
| x_velocity |  |  |  |  |  |  |  |
| y-velocity |  |  |  |  |  |  |  |
| z_velocity |  |  |  |  |  |  |  |
| vector_source |  |  |  |  |  |  |  |
| utc-st-time |  |  |  |  |  |  |  |
| sat_binary_time |  | 1 |  |  |  |  | 1 |
| slock_stop |  |  |  |  |  |  |  |
| leap_ute |  |  |  |  |  |  |  |
| leap_err |  |  |  |  |  |  |  |
| producterr | $1 \quad 1$ | -1. | 1 | $1 \quad 1$ | -1 | 1 | 1 |
| 00:00 |  |  | 00:00 |  | 16:00 |  |  |
| 18/06/2009 |  |  |  |  |  |  |  |

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y-position
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$\square$ leap_ute<br>$\square$ vectar sisurce<br>phase<br>$\square$ proc_time<br>filename

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y-position
sensing sto
proc_center
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producterr
sat_binary-time
y_velocity
x-position
sensing start
acquisition_station
y-relocity
sensing start
acquisition_station
19/06/2008

product err
sat_inary-time
y_velocity
x-position
sensing_start
acquisition_station
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acquisition_station

product err
sat_inary-time
y_velocity
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acquisition_station

$\square$ stop」at $\square$ num_missing_Sifs $\square$ ISP_errars significant $\square$ startlat
num_error_ SPs
$\square$ num_error
ADFs validity check
 $\square$ stop」at $\square$ ISP_errors significant $\square$ startat
num_errord SPs $\square$ sot_track $\square A D F s$ validity cheak
 $\square$ stop」at

 $\square$ stop」at



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[^0]:    — sea/ice ku retrack percent
    ice1 s retrack percent
    20 band percent
    I1b proceasing errors significance flog
    inyentaried production

